Cosmic Explorer Optical Design Status

Paul Fulda

Jon Richardson University of Florida University of California, Riverside

On behalf of the CE Optical Design Team



CE Symposium – April 23, 2024









Upgrade Path for Fused-Silica Interferometers

LIGO O4 configuration:

- ~350 kW laser power in the arm cavities
- ~ 5 dB frequency-dependent squeezing

| Quantity | A+ (O5) | A [#] (O6) |
|----------------------|---------|---------------------|
| Arm length (km) | 4 | 4 |
| Wavelength (nm) | 1064 | 1064 |
| Mirror mass (kg) | 40 💻 | → 100 |
| Mirror diameter (cm) | 34 💻 | ➡ 46 |
| Arm power (MW) | 0.8 | 1.5 |
| Squeezing (dB) | 6 | 10 |



Upgrade Path for Fused-Silica Interferometers



Cosmic Explorer: Why Not Just Scale up LIGO Design?

1) Unique challenges arise from a 10x longer arm length (CE-G2300033)

- Minimum beam size for 40 km arms is ~12 cm. For < 1 ppm clipping loss on ITMs, require ~70 cm ITMs. Beamsplitter should be √2 bigger* (at 45° AOI). 1 m diameter unfeasible?
 ➡ Consider alternate layouts with a different beamsplitter location
- SEC resonance approaches detection band with 40 km or 20 km arms (f_s ∝ 1/√L_s)
 ⇒ SEC length must be kept to < 200 m (40 km arms) or < 90 m (20 km arms)
- FSR of 40 km arms is 3.75 kHz. With same arm finesse, DARM pole is 10x lower (f_p ∝ 1/L_a)
 ▶ Need 10x higher SEC finesse to recover same bandwidth

Cosmic Explorer: Why Not Just Scale up LIGO Design?

1) Unique challenges arise from a 10x longer arm length (CE-G2300033)

- Minimum beam size for 40 km arms is ~12 cm. For < 1 ppm clipping loss on ITMs, require ~70 cm ITMs. Beamsplitter should be √2 bigger* (at 45° AOI). 1 m diameter unfeasible?
 ➡ Consider alternate layouts with a different beamsplitter location
- SEC resonance **approaches detection band** with 40 km or 20 km arms $(f_s \propto 1/\sqrt{L_s})$ • SEC length must be kept to < 200 m (40 km arms) or < 90 m (20 km arms)
- FSR of 40 km arms is 3.75 kHz. With same arm finesse, DARM pole is 10x lower (f_p ∝ 1/L_a)
 ⇒ Need 10x higher SEC finesse to recover same bandwidth
- With a 10x lower arm cavity FSR, nearly all higher-order mode (HOM) resonances will lie in the observation band
 - Precision mode-matching is critical to suppress noise couplings, squeezing loss, and squeezing angle mis-rotation around the frequencies of these resonances

Impact of SEC **Mode-Mismatch**

In-band HOM resonances lead to a coherent mode-scattering effect:

TEMO0 \rightarrow IG10 \rightarrow TEMO0*

*having accumulated a *different* phase relative to the unscattered TEM00 field (see McCuller et al. 2021)

Results in an effective rotation of the squeezing angle relative to the interferometer's readout quadrature ("anti-squeezing") at frequencies near HOM resonances

Example Quantum Noise Budget

with 1% SEC mode-mismatch to arms



Impact of SEC Mode-Mismatch

In-band HOM resonances lead to a **coherent mode-scattering** effect:

 $\mathsf{TEM00} \rightarrow \mathsf{LG10} \rightarrow \mathsf{TEM00}^*$

*having accumulated a *different* phase relative to the unscattered TEM00 field (see <u>McCuller *et al.* 2021</u>)

Results in an **effective rotation of the squeezing angle** relative to the interferometer's readout quadrature ("anti-squeezing") at frequencies near HOM resonances

Example Quantum Noise Budget

with 0.1% SEC mode-mismatch to arms



Cosmic Explorer: Why Not Just Scale up LIGO Design?

2) Thermal distortions are a much stronger design driver (LIGO-G2300624)

CE's quantum noise target assumes:

- **1.5 MW** of circulating arm power 4x higher than aLIGO O4
- 10 dB of frequency-dependent squeezing
 - Requiring < 500 ppm SEC loss
 10x lower than LIGO A+



Cosmic Explorer: Why Not Just Scale up LIGO Design?

2) Thermal distortions are a much stronger design driver (LIGO-G2300624)

CE's quantum noise target assumes:

- **1.5 MW** of circulating arm power 4x higher than aLIGO O4
- **10 dB** of frequency-dependent squeezing
 - Requiring < 500 ppm SEC loss
 10x lower than LIGO A+

Overcoming thermal distortions requires:



- Pick-off port locations to **directly sense mode-matching** between cavities
- Cavity Gouy phases chosen to minimize impact on squeezing (avoid HOM co-resonances)
- Higher-precision wavefront control, beyond radius of curvature correction

Does 500 ppm SEC Loss Preclude 45° Beamsplitter AOI?

With ~10 kW in the PRC, **thermal lensing in the beamsplitter** substrate is a significant effect

- Uncompensated HOM scattering loss could consume the majority of the SEC loss budget
- But limited capability to thermally compensate at 45° AOI

Lower AOI on the beamsplitter:

- Improves the effectiveness of thermal compensation 100x
- Reduces the beamsplitter size requirement by a factor of $\sqrt{2}$

Single-Pass Beamsplitter HOM Scattering with optimal thermal compensation





Favored CE Interferometer Topologies



- ~1° beamsplitter AOI
- Static lens polished onto ITM AR surface



- 45° beamsplitter AOI
- Will benefit from static ITM lens.
- A lower-risk option, *if* beamsplitter thermal lensing is manageable

PRC and SEC design progress: eigenmodes



Work on this topic by Sagar Gupta, Liu Tao, Matt Todd, Kevin Kuns, ++

PRC and SEC design progress: geometric layout



Work on this topic by Matt Todd and Pooyan Goodarzi





500 ppm SEC Loss Precludes Compensation Plates

Based on aLIGO AR coatings, expect high-angle scattering loss of **up to 200 ppm** (roundtrip) per compensation plate (CP)



500 ppm SEC Loss Precludes Compensation Plates

Requires a *qualitatively* new approach to wavefront control, with actuation on **fine spatial scales** (2-5 cm) and **low displacement noise** (RIN < $10^{-9}/\sqrt{Hz}$)





Prototype test at LIGO Lab-Caltech

Measured temperature profile



PRC Mode-Matching

- Two additional low-order (RoC) actuation points
- Less stringent loss requirement allows for additional optics in PRC path
- Independent control of SEC and PRC mode-matching
- > 20° Gouy phase separation between PR3 and PRM





Summary of Technical Challenges

- The many corner layouts studied for CE have been reduced to two contenders, the "Long Reverse aLIGO" and "Long Crab." Are there any obvious showstoppers for either of these?
- One challenge with 40 km arms is that an FSR of 3.75 kHz means every HOM resonance is in-band. What does this mean for quantum noise performance and laser noise coupling with imperfect mode matching?
- An additional 40 km arm challenge is sensing CARM, as the arm bandwidth is too low to do what aLIGO currently does. **Are there any alternatives?**
- So far, parametric instabilities have been regarded as a secondary concern, to be addressed later in the design process. Is this prioritization appropriate?
- Which of these risks/topics, or others not listed, are crucial to study now for placing requirements on the <u>infrastructure/facility design</u>?

Extra Slides

Reference: Basic CE Design Parameters

| Quantity | CE |
|----------------------|------|
| Arm length (km) | 40 |
| Wavelength (nm) | 1064 |
| Mirror mass (kg) | 320 |
| Mirror diameter (cm) | 70 |
| Arm power (MW) | 1.5 |
| Power on BS (kW) | 10 |
| Arm Finesse | 450 |
| SRM T (%) | 2 |
| Squeezing (dB) | 10 |

| Quantity | CE |
|----------------------|--------|
| PRM T (%) | 3 |
| SEC loss (ppm) | 500 |
| Roundtrip loss (ppm) | 40 |
| Arm pole (Hz) | 4.2 |
| CARM pole (Hz) | 0.02 |
| DARM pole (Hz) | 825 |
| SEC length (m) | 80-200 |
| FC length (km) | 4 |
| Beam size on TM (cm) | 12 |

Beamsplitter in a strongly converging telescope: concerns



- Especially at 45deg AOI, coating reflectivity will vary across the beam spot.
- Linear dependence of reflectivity on AOI actually just has a mode matching effect.
- Combines with the more obvious mode matching effect (see sketch).

In words, what matters is directly the Rayleigh length of the beam passing through the BS. For example, if we assume a BS placement tolerance of 5mm, and a maximum acceptable loss of 25ppm, the minimum acceptable Rayleigh length is

$$z_{R,min} = \frac{5\text{mm}}{\sqrt{25 \cdot 10^{-6}}} = 1\text{m}$$
(12)

Matthew Todd and Stefan Ballmer: CE-T2300014

CARM Feedback Main problem

| | | | Advanced LIGO | Cosmic Explorer | | |
|--|---------------|----|------------------|--------------------|--------|---------|
| For Cosmic Explorer, the arms will be 40 km long. The free-spectral range of LIGO is 38 kHz. The free-spectral range of Cosmic Explorer is 3.8 kHz | | | | | 4 km | 40 km |
| | | | | FSR | 38 kHz | 3.8 kHz |
| L = 4 km | Advanced LIGO | VS | | CARM pole | 0.4 Hz | 0.04 Hz |
| | | | Cosmic Explorer | | | |
| | | | I = 40 km | | | |

- 40 KIII

Problem: LIGO's current frequency stabilization bandwidth is around 30 kHz. However, the controller cannot extend beyond the FSR due to the overcoupled arm cavity phase dynamics. Additionally, the extremely low linewidth (0.04 Hz) makes the CE shot noise limit insufficient at 500 Hz.

Solution: do not rely on CARM for HF feedback

Do not rely on the interferometer for frequency noise suppression

Instead, use two long input mode cleaners

First IMC is high-bandwidth to reach shot noise limit Second IMC is low-bandwidth to passively filter noise Main interferometer will also strongly filter noise

Advantages:

Long cavity is a better frequency reference
 No feedback from IFO required



Simulation tools for CE optical design

- Finesse 3
 - For noise couplings, quantum noise calc., closed loop controls.
- pyGWINC
 - Noise budgets, science metrics.
- SIS
 - High-order scattering, stray light modeling.
- GTrace, Zemax, ...
 - Geometrical layouts, ghost beams.
- FEA tools
 - COMSOL, ANSYS
 - FEniCSx (open-source)
- Time domain optical modeling software.
 - Lock acquisition, glitch response, ...
- ...others we should be aware of?
- ...physics that is needed but not covered by these?

Optical design team organization

- CE mailing list: optdes@cosmixeplorer.org
- Weekly Zoom calls, Monday 4pm EST. Alternating:
 - Week A "formal" call, with progress updates.
 - Agenda, notes and recordings stored on <u>CE DCC here</u> under different document versions.
 - Week B "informal" workshop-style call.
 - Students encouraged to bring modeling questions etc.
- Mattermost Channel used for discussion among project members.
- Mattermost Board used for coordination of tasks.
- Gitlab instance used for optical design modeling repositories.

| CE optical design | | 🛆 Share | | | |
|---|---|---|--|--|--|
| Progress Tracker Y Pro | perties Group by: Status Filter | Sort Q Search cards | | | |
| Not Started 10 + | In Progress 4 ···· + | Completed 🖗 4 … + | | | |
| Calculate beamsplitter reflectivity variation over beam size for curved wavefront. | Corner layout-agnostic recycling cavity design | Calculate beam splitter mechanical modes vs size for fixed aspect ratio | | | |
| 1. HIGH 🔥 | Investigate Gouy phase effects | Make Corner Layout git repo Make IMC design git repo | | | |
| 😭 Investigate mode hopping | on SQZ degradations and carrier/sideband PRGs and error signals | | | | |
| Ake initial "default" mode- matched Finesse Crab 1 model | Make RH and FROSTI profiles for CE test masses | A Make initial "default" mode- matched Finesse Split | | | |
| 🔗 Make initial "default" mode- | 1. HIGH 🔥 | Telescope model | | | |
| matched Finesse Crab 2 model | 🕞 Write up technical note on | + New | | | |
| Make initial "default" mode- | corner layout down select | | | | |
| model | + New | | | | |

| main ~ cosmic-explorer- | corner-layout / + ~ History | Find file Edit ~ Code |
|--|---------------------------------|-----------------------|
| wpdate readme Kevin Kuns authored 1 | 3 hours ago | 43b9b0e7 C |
| Name | Last commit | Last updat |
| PRC_Design | add ipynb to lfs | 3 days ag |
| 🖹 SRC_Design | add ipynb to lfs | 3 days ag |
| 🗅 mechanical_modes | add beamsplitter mechanical mod | 2 weeks ag |
| h mode_matching | ARM to ouput mode matching; Ad | 2 days ag |
| ♦ .gitattributes | add ipynb to lfs | 3 days ag |
| ♦ .gitignore | add beamsplitter mechanical mod | 2 weeks ag |
| H+ README.md | update readme | 13 hours ag |
| n conftest.py | add pytest stuff | 1 month ag |

Optical design NSF award

Design work split into 4 work packages:

Core optical design

Interferometer sensing and control.

Laser stabilization and lock acquisition.

Readout and quantum enhancement.

Key project deliverables:

Conceptual design of CE interferometers, performance consistent with science targets.

Subsystem requirements specifications.

Interferometer noise budget (beyond fundamental noises).

Reference simulation models for CE IFOs.

| Work package | Resources (FTE) | Deliverables | Milestones |
|---|--|--|---|
| Core Interferometer | UF Faculty (PF) 1 wk + acad. UF Faculty (DBT) 1 wk + acad. SU Faculty (SB) 1 wk + acad. MIT Scientist (KK) 12.5% MIT Scientist (LB) acad. UF Postdoc 30% UF Engineer (JG) 4% Y2, 8% Y3 | Initial design of the interferometer topology and corner telescope parameters. Code base and parameter files for full interferometer optical simulations. Noise budget for the full interferometer. Design requirements document for related subsystems interfacing with the optical design. Draft CAD layout of major optical components within notional vacuum enclosures. | Y1. Initial design of the overall interferometer topology and corner station telescopes complete. Y2. Design for arm cavity parameters, recycling cavity parameters, beam sizes on optics. Y3. Noise budgets for full interferometer and key subsystems complete. |
| Interferometer Sensing and Control | UF Faculty (PF) 1 wk + acad. MIT Scientist (KK) 12.5% MIT Scientist (LB) acad. UF Postdoc 30% SU postdoc 30% | Initial design of sensors and actuators for length and angular control. Definition of the phase modulation sidebands. Model files and parameters for sensing matrices. Model files and parameters of cross-couplings between ISC components. Requirements document for design of ISC scheme and interfacing subsystems. | Y1. Establish sensing ports and interfaces, and develop initial controls models. Y2. Commission interferometer control and noise simulations, converge with core interferometer design on key sensing and actuation parameters. Y3. Model cross-couplings and compile noise budget. |
| Laser Stabilization and Lock Acquisition | SU Faculty (CC) 2 wks + acad. SU Faculty (GM) 1 wk + acad. SU Postdoc 30% | Initial design for laser stabilization system. Initial design of input mode cleaner including length and cavity geometry. Simulation files and model parameters for realistic laser noise and coupling to GW readout. Lock acquisition system and procedure for CE interferometers. | Y1. Initial design concept of frequency noise suppression system complete. Y2. Initial design of lock acquisition system and procedure. Y3. Model of laser noise couplings. |
| Readout and Quantum Enhancement | CIT Faculty (LM) 2 wks + acad. SU Faculty (GM) 1 wk + acad. CIT Postdoc 25% | Output path design document including optical parameters for output telescope, output mode cleaner cavity, and output Faraday isolator(s) Squeezer and filter cavity optical design. Backscatter and controls noise modeling code base. | Y1. Initial design of output cavities, telescopes, readout scheme. Y2. Modeling of potential squeezer degradations, design sensing and control scheme for output path. Y3. Noise analysis of gravitational-wave readout. |

Optical design work flowchart % Georgia Mansell



We are here

CE optical design basics



Interferometers are frequency-dependent squeezing-enhanced dual-recycled Fabry-Perot Michelson interferometers (like A+).

40km and 20km arm lengths.

Longer arms (at same finesse) means lower FSR (and cavity pole).

SEC finesse must be higher to retain broadband response.

Beam radius on TMs ~12cm.

1.5 MW circulating arm power.

Stable recycling cavities.

Balanced homodyne readout.

SEC length effect on sensitivity to post-merger signals



In CE the SEC resonance falls within the detection band (unlike aLIGO), especially for long SEC.

This can reduce sensitivity around 2kHz, where BNS post-merger signal lives. 80% reduction from optimal post-merger sensitivity when:

 $\begin{array}{l} L_{SEC} \ 20m \rightarrow 200m \ (CE \ 40km) \\ L_{SEC} \ 25m \rightarrow 90m \ (CE \ 20km \\ post-merger \ tuned). \end{array}$

For reference, aLIGO $L_{SRC} \sim 55m$. Optical design challenge is to keep SEC short within other constraints (e.g. beam size reduction from arms to output).

Kevin Kuns: CE-G2300033

SEC length effect on sensitivity to post-merger signals

20km

| Configuration | \mathcal{F}_{a} | L _s [m] | T _s [%] | $ ho_{ m pm}^{(m max)}$ | $ ho_{ m pm}^{(90)}$ | $ ho_{ m pm}^{(50)}$ | BNS range [Mpc] |
|-----------------|---|--|--|---|---|---|---|
| Optimal PM | 450 | 24 | 0.45 | 12.0 | 10.7 | 8.1 | 1700 |
| 90 % optimal PM | 450 | 63 | 0.64 | 10.7 | 9.1 | 6.4 | 1800 |
| 80 % optimal PM | 450 | 89 | 1.13 | 10.7 | 8.0 | 5.8 | 2100 |
| Compact binary | 450 | 89 | 4.00 | 10.6 | 7.0 | 5.4 | 2600 |
| Optimal PM | 800 | 20 | 0.28 | 9.3 | 8.3 | 6.3 | 1700 |
| 90 % optimal PM | 800 | 42 | 0.58 | 9.4 | 7.2 | 5.4 | 2000 |
| 80 % optimal PM | 800 | 64 | 0.98 | 9.5 | 6.5 | 4.8 | 2300 |
| Compact binary | 800 | 64 | 2.30 | 9.7 | 6.1 | 4.7 | 2600 |
| | | | | | | | |
| | | | | (| (00) | | |
| | \mathcal{F}_{a} | L _s [m] | T _s [%] | $\rho_{\rm pm}^{(\rm max)}$ | $ ho_{ m pm}^{(90)}$ | $ ho_{ m pm}^{(50)}$ | BNS range [Mpc] |
| | Fa 450 | L _s [m] 20 | T _s [%] 2.00 | ρ _{pm} ^(max) 13.7 | ρ(90) ρ _{pm} 7.9 | $ ho_{ m pm}^{(50)}$ 6.2 | BNS range [Mpc] 3700 |
| | Fa 450 450 | L _s [m] 20 100 | T _s [%] 2.00 2.00 | ρ _{pm} ^(max) 13.7 13.1 | ρ ⁽⁹⁰⁾ ρ _{pm} 7.9 6.2 | $ ho_{ m pm}^{(50)}$ 6.2 5.0 | BNS range [Mpc] 3700 3700 |
| | <i>F</i> _a 450 450 450 | L _s [m] 20 100 200 | T _s [%] 2.00 2.00 2.00 | ρ(max) ρpm 13.7 13.1 12.4 | (90) Ppm 7.9 6.2 4.8 | ρ(50) ρ _{pm} 6.2 5.0 3.7 | BNS range [Mpc] 3700 3700 3700 |
| km | <i>F</i> _a 450 450 450 450 | L _s [m] 20 100 200 400 | T _s [%] 2.00 2.00 2.00 2.00 | ρ _{pm} ^(max) 13.7 13.1 12.4 11.5 | ρ _{pm} ⁽⁹⁰⁾ 7.9 6.2 4.8 3.6 | ρ _{pm} ⁽⁵⁰⁾ 6.2 5.0 3.7 2.5 | BNS range [Mpc] 3700 3700 3700 3700 |
| km | Fa 450 450 450 450 800 | L _s [m] 20 100 200 400 20 | T _s [%] 2.00 2.00 2.00 2.00 1.10 | ρ(max) ppm 13.7 13.1 12.4 11.5 12.4 | $\begin{array}{c} \rho_{\rm pm}^{(90)} \\ 7.9 \\ 6.2 \\ 4.8 \\ 3.6 \\ \hline 6.8 \end{array}$ | ρ _{pm} ⁽⁵⁰⁾ 6.2 5.0 3.7 2.5 5.3 | BNS range [Mpc] 3700 3700 3700 3700 3700 |
| km | $\begin{array}{c c} & \mathcal{F}_{a} \\ \hline 450 \\ 450 \\ 450 \\ \hline 450 \\ \hline 800 \\ 800 \\ \hline 800 \\ \hline \end{array}$ | L _s [m] 20 100 200 400 20 20 100 | T _s [%] 2.00 2.00 2.00 2.00 1.10 1.10 | ρ _{pm} ^(max) 13.7 13.1 12.4 11.5 12.4 11.6 | $\rho_{pm}^{(90)} \\ 7.9 \\ 6.2 \\ 4.8 \\ 3.6 \\ 6.8 \\ 4.8 \\ 4.8 \\ \end{cases}$ | $\begin{array}{c} \rho_{\rm pm}^{(50)} \\ 6.2 \\ 5.0 \\ 3.7 \\ 2.5 \\ 5.3 \\ 3.7 \end{array}$ | BNS range [Mpc] 3700 3700 3700 3700 3600 3600 |
| km | Fa 450 450 450 450 800 800 800 | L _s [m] 20 100 200 400 20 100 200 | T _s [%] 2.00 2.00 2.00 1.10 1.10 1.10 | ρ _{pm} 13.7 13.1 12.4 11.5 12.4 11.6 10.9 | $\begin{array}{c} \rho_{\rm pm}^{(90)} \\ 7.9 \\ 6.2 \\ 4.8 \\ 3.6 \\ 6.8 \\ 4.8 \\ 3.7 \end{array}$ | $\begin{array}{c} (50)\\ \rho_{pm}\\ 6.2\\ 5.0\\ 3.7\\ 2.5\\ 5.3\\ 3.7\\ 2.5\\ 3.7\\ 2.5\\ \end{array}$ | BNS range [Mpc] 3700 3700 3700 3700 3600 3600 3600 |
| km | Fa 450 450 450 450 800 800 800 800 | L _s [m] 20 200 400 200 100 200 400 | T _s [%] 2.00 2.00 2.00 1.10 1.10 1.10 1.10 | ρ _{pm} (max) 13.7 13.1 12.4 11.5 12.4 11.6 10.9 10.2 | $\begin{array}{c} \rho_{\rm pm}^{(90)} \\ 7.9 \\ 6.2 \\ 4.8 \\ 3.6 \\ 6.8 \\ 4.8 \\ 3.7 \\ 3.4 \end{array}$ | $\begin{array}{c} \rho_{\rm pm}^{(50)} \\ 6.2 \\ 5.0 \\ 3.7 \\ 2.5 \\ 5.3 \\ 3.7 \\ 2.5 \\ 1.7 \end{array}$ | BNS range [Mpc] 3700 3700 3700 3700 3600 3600 3600 3600 |

40k

Kevin Kuns: <u>CE-G2300033</u>

SEC length effect on sensitivity to post-merger signals

| Configuration | \mathcal{F}_{a} | L _s [m] | T _s [%] | $\rho_{pm}^{(max)}$ | $ ho_{ m pm}^{(90)}$ | $ ho_{ m pm}^{(50)}$ | BNS range [Mpc] |
|-----------------|-------------------|--------------------|--------------------|---------------------|----------------------|----------------------|-----------------|
| Optimal PM | 450 | 24 | 0.45 | 12.0 | 10.7 | 8.1 | 1700 |
| 90 % optimal PM | 450 | 63 | 0.64 | 10.7 | 9.1 | 6.4 | 1800 |
| 80 % optimal PM | 450 | 89 | 1.13 | 10.7 | 8.0 | 5.8 | 2100 |
| Compact binary | 450 | 89 | 4.00 | 10.6 | 7.0 | 5.4 | 2600 |
| Optimal PM | 800 | 20 | 0.28 | 9.3 | 8.3 | 6.3 | 1700 |
| 90 % optimal PM | 800 | 42 | 0.58 | 9.4 | 7.2 | 5.4 | 2000 |
| 80 % optimal PM | 800 | 64 | 0.98 | 9.5 | 6.5 | 4.8 | 2300 |
| Compact binary | 800 | 64 | 2.30 | 9.7 | 6.1 | 4.7 | 2600 |

Question to consider:

Maintaining the post-merger sensitivity places what seems to be a challenging constraint on SEC length for the 20km IFO. Might we need to review a science case trade on this item?

Laser wavelength: accommodating 2µm

CE baseline design is for 1064 nm.

Potential upgrades include a Voyager-like configuration in the future.

Cryogenic silicon test masses.

Laser wavelength required to change to $\sim 2 \,\mu m$.

Challenge is to avoid *facility* constraints that will make this "difficult".

Examples:

Baseline beam size for 2 µm over 40 km is 16.5 cm Would want higher arm finesse (~3x) to take advantage of better thermal handling (which would also remove benefit of 20 km post-merger tuning) Section 8.4 of the horizon study.

Question: To what degree do we need to keep these things in mind as we proceed with the 1064nm design?

Frequency noise mitigation

Low arm FSR precludes using arms as in-band frequency reference (UGF too low).

Alternative scheme uses a long (100m+) input mode cleaner as frequency reference. Second mode cleaner may be needed for passive filtering (also IMC refl. Mode cleaner).



Matthew Todd and Peter Zhou Syracuse University





Craig Cahillane, Georgia Mansell, Daniel Sigg, Opt. Express 29, 42144-42161

Mode Sensing and Control Project Summary

Actuators Work Package



Summary of MSC Challenges

- MSC will drive optical topology of entire interferometer

 E.g., Beamsplitter AOI
- CE's quantum noise target (1.5 MW / 10 dB SQZ) requires:
 - <1% mode-mismatch between interferometer cavities
 - <500 ppm loss in Signal Extraction Cavity (SEC)
- Requires a new generation of wavefront actuators
 - Apply more accurate wavefront correction to test masses under extreme thermal loading
 - Eliminate the transmissive compensation plates relied on by LIGO
- Requires closed-loop sensing and control of these actuators