## **∂**TRIUMF

## DarkLight Trigger System Status

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DarkLight Collaboration Meeting



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## **Trigger System Overview**



Goals:

 Prompt data collection in the GEMs → requires better than 200 ps timing resolution

#### Provide additional accuracy verification in hit position determination

## **Trigger Anatomy**





## **Equipment Status**

- 3/4 prototype paddles assembled
  - 2 will remain as is
  - 2 to be used in making the experiment's paddles
- 11 scintillators available
  - 7 wrapped and ready
- All SiPM boards ready and at TRIUMF
- Underway: small scale design improvements



Assessing Trigger Performance

## **Time-of-Flight Studies**

- Goal: prove the system can accurately measure time
- Measuring average arrival difference between the paddles with a variety of vertical spacings between the two paddles

$$\frac{t_8 - t_5}{2} - \frac{t_4 - t_1}{2}$$



7

Cosmic data

8

## **Time-of-Flight Studies**



- Apparent gap distance ~67 % of physical distance
- Difference due to uncertainty in the system's definition of one second



Source data

## **Timing Resolution**



- Typical for time difference measurements ~ 320 ps
- Typical for absolute time measurements ~ 270 ps
- Best timing resolution so far: 243 ps (absolute time) and 228 ps (TOF)

Source data

10

## **Timing Resolution**

	Тор		Bottom	
	$t_4 - t_1$	$t_3 - t_2$	$t_{8} - t_{5}$	$t_7 - t_6$
Mean pulse width [ns]	39.3	38.5	49.3	48.2
Timing resolution [ns]	0.299	0.310	0.388	0.402

	Left scintillators (1 4/5 8)	Right scintillators (2 3/6 7)	
Mean pulse width ratio	0.80	0.80	
Timing resolution ratio	0.77	0.77	
	Тор	op scintillator/bottom scintillator	

All time differences are restricted to coincidence events between the upper/lower scintillator

## **Position Resolution**

Goal: Support GEMs hit location identification by providing an additional verification system

Improves background filtering

Examined by stacking paddles to enable coincidences and varying a Sr-90 source over the length of a scintillator





12

## **Position Resolution**



Slope uncertainty:  $\sim 0.03$  ns/cm y-intercept uncertainty:  $\sim 0.3$  ns

Source data

## **Position Resolution**

- Studied four runs with the source position varied by 4.0 cm
- Convert time axis of time difference plot to position

	Left scintillator (14-58)	Right scintillator (23-67)
$\sigma$ upper scintillator [cm]	2.1	2.2
$\sigma$ lower scintillator [cm]	2.8	2.5



#### **Currently Investigating: Cable Length Effect**



14

#### **Currently Investigating: Cable Length Effect**



Improving Trigger Performance

## **Cooling Techniques**

- Replaced plastic spacer with a copper spacer
- Cooled the SiPMs from 36°C to 30°C
- Adds significant height to the system, we are actively investigating solutions



- 3 - 5 mm height addition

## **Next Steps: Peltier Introduction**





Gallina, G., Giampa, P., et al, 2019. Characterization of the Hamamatsu VUV4 MPPCs for nEXO. https://arxiv.org/pdf/1903.03663

## **Ongoing: Improving Documentation**

- Trigger user manual development underway
- Four task specific assembly manuals ready
- Cabling diagram under revisions



DarkLight - Trigger Prototype Signals & Systems Diagram

Diagram courtesy of Karm Gill

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### Thank you Merci

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# Discovery, accelerated



#### **Position Resolution – Absolute Time**





#### **Position Resolution – Widths**





#### **Cable length investigation: gains**

