DL DAQ/SlowCtrl/Rates

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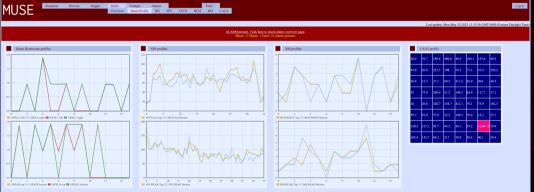
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Slow Ctrl

Suggestion: Use system we employed in OLYMPUS and MUSE

- » EPICS based
- » PSQL database + python datapump + flask web gui
- » Data also streamed into DAQ



GEM DAQ

- » Components: 8+5=13 APV cards per plane.
- » MPD4 digitizer: up to 15 APV cards per MPD
- » Standard readout via VME
- » Can do 1, 3 or 6 frames
 - » 3 frames gives us time resolution, probably good to reduce multi-hit confusion

Data rates / speeds

- » At MUSE: 120 μs for 4 APV 6 frames = 12kByte/Event \rightarrow 100 MByte/s (2x data reduction with firmware upgrade possible)
- » Time dominated by VME transfer.
- » Assume: 1 MPD / plane, 3 frames, all channels
 - » 78 kByte per event.
 - » 100% dead at 1250 Hz if read out via one crate (but larger data block might improve speed)
 - » 2.5kHz with better packing
- » We expect 200 Hz for 13@31, 700Hz for 17@55.
 - » Not crazy bad, but not ideal.
 - » This assumes trigger-level single bunch resolution, no additional background!

Alternative readouts

Alternative readout options:

- » Split into multiple MPD4 (-> 5kHz @2, 10kHz@4, but need more VME CPUs)
- » Use Fiber interface
 - » Aurora protocol (implemented, need VTP?, 2.5Gbit/s per MPD) 31kHz, need special electronics
 - » Direct ethernet (not implemented, 1 GBit/s or maybe 2.5 GBit/s?) 12.5kHz/31kHz, only need ethernet cards

Disk requirements

We will save about

- » 7.6 MByte/s for 13@31 (26 TB for 1000h. Small raid?)
- » 26 MByte/s for 17@55
- » 38 MByte/s for 1kHz (130TB for 1000h. Biggish raid)

This is for uncompressed but word-packed data.

Busy / synchronization

Need to distribute trigger to MPD4

- » Must have fixed latency<4 μs
- Fully locked or free running?
 - » Free running:
 - » MPD4 can raise busy flag if FIFO is above threshold
 - » Generate MIDAS event for each fully read event
 - » Fully locked
 - » Not sure if we can use the busy. Threshold=1?
 - » Need trigger to set busy until MPD4 can set busy. Wait for busy or fixed time.

Software

- » Will use MIDAS for DAQ
- » Strongly suggest to use COOKER framework for analysis:
 - » Used in OLYMPUS, MUSE, J-PARK, and DL
 - » Can read MIDAS files (even compressed with xz), map to root file
 - » Break down analysis into independent plugins decouple development of different aspects
 - » Thin framework on top of root

What we already have for cooker

- » Analysis configuration via XML based init file
- » Run database (postgresql)
- » Can chain plugins, can split to run in parallel, compatible with clusters
- » Command line and GUI versions. Can visualize event per event.
- » Handling of MC weights etc.
- » Have code for
 - » Mapping
 - » GEM analysis
 - » MC integration, generators
 - » Slow Ctrl
 - » many more