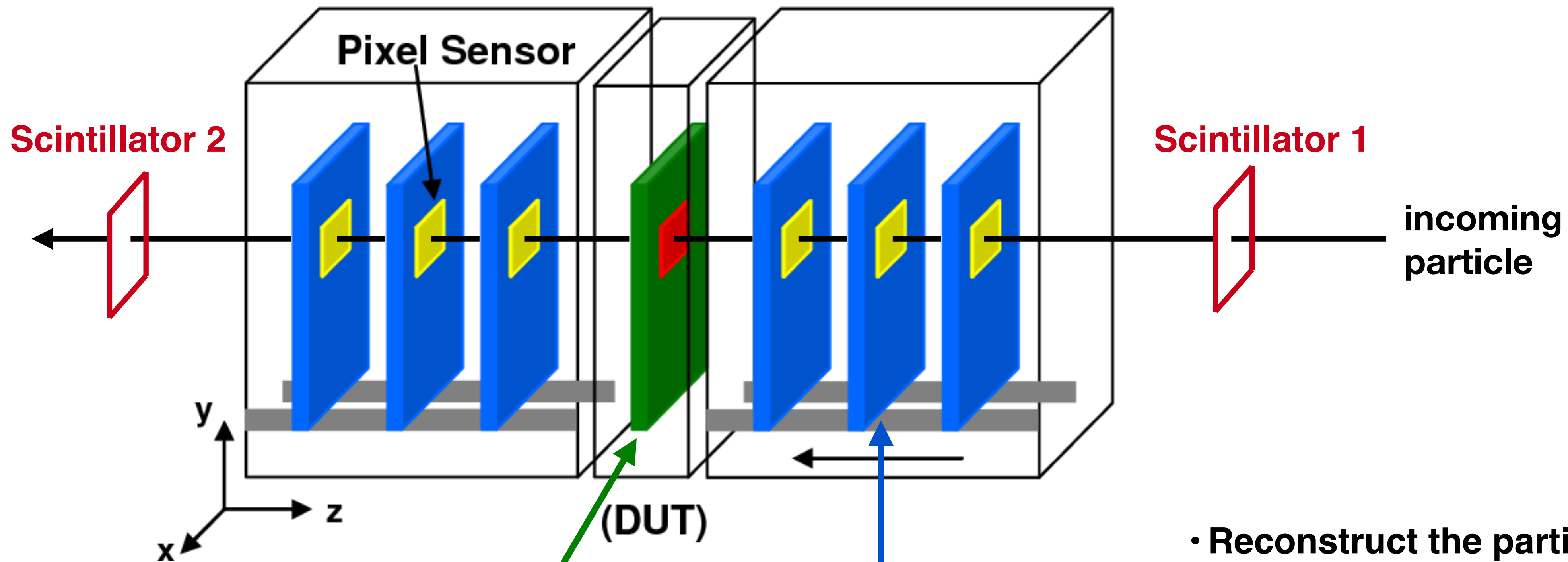


**Recent activities at CERN:**

**test beams with ALPIDE telescope**

# What is a telescope and how does it work?

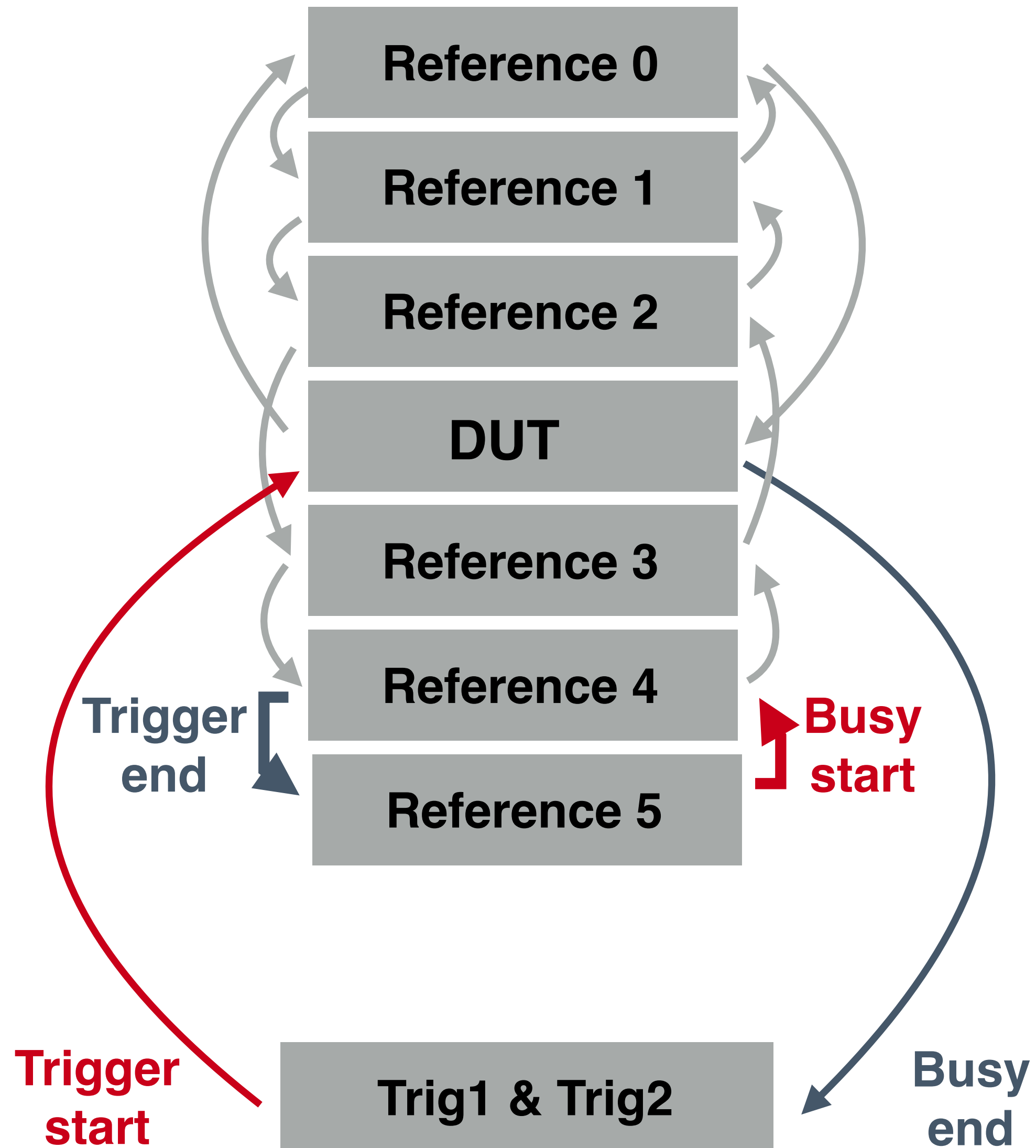


Device Under Test (DUT)

Several layers of reference planes equipped with a known sensor

- **Reconstruct the particle trajectory** using the references with known resolution
- **Identify the “ideal” point of intersection** with DUT
- **Hit association on the DUT** to estimate the DUT resolution and efficiency

# Trigger/busy logic

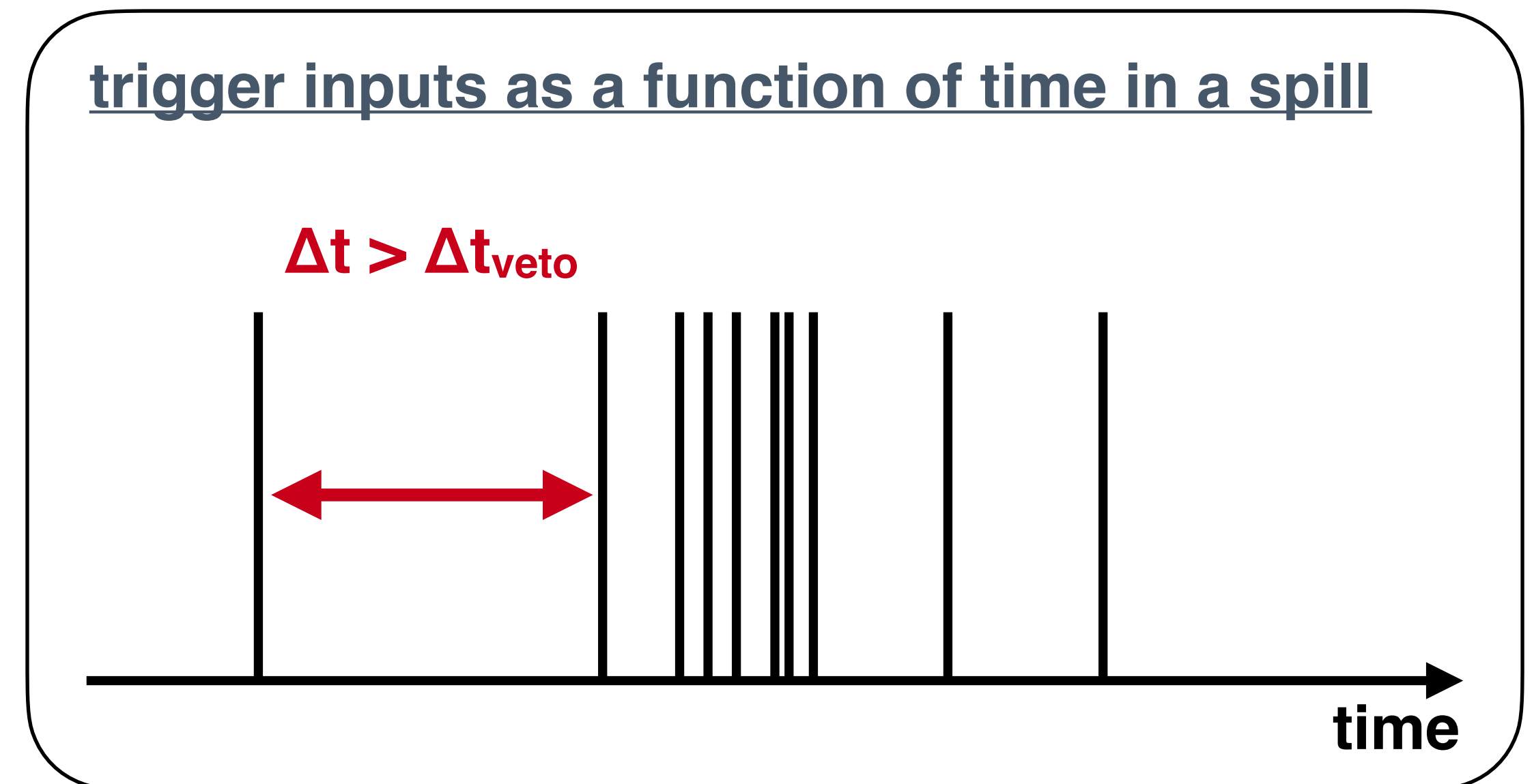


## Trigger coincidence (PMT1 AND PMT2):

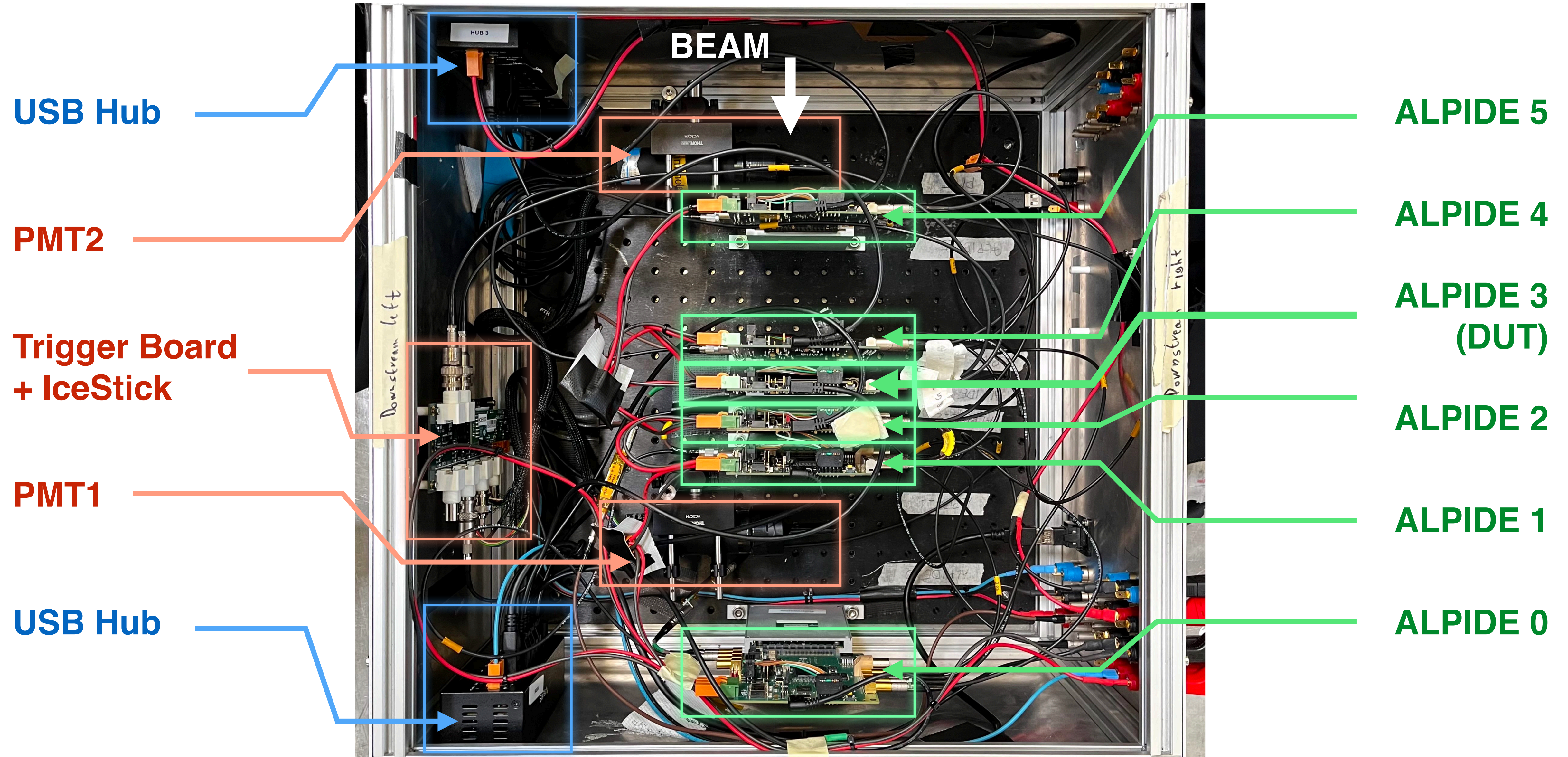
- logic end between the signals coming from the two PMTs

## Trigger veto to mitigate pileup:

- accept a trigger only if no trigger input were received was received in a given time windows



# Telescope setup



# Telescope calibration, alignment and operation (summary)

## Telescope installation at PS test-beam

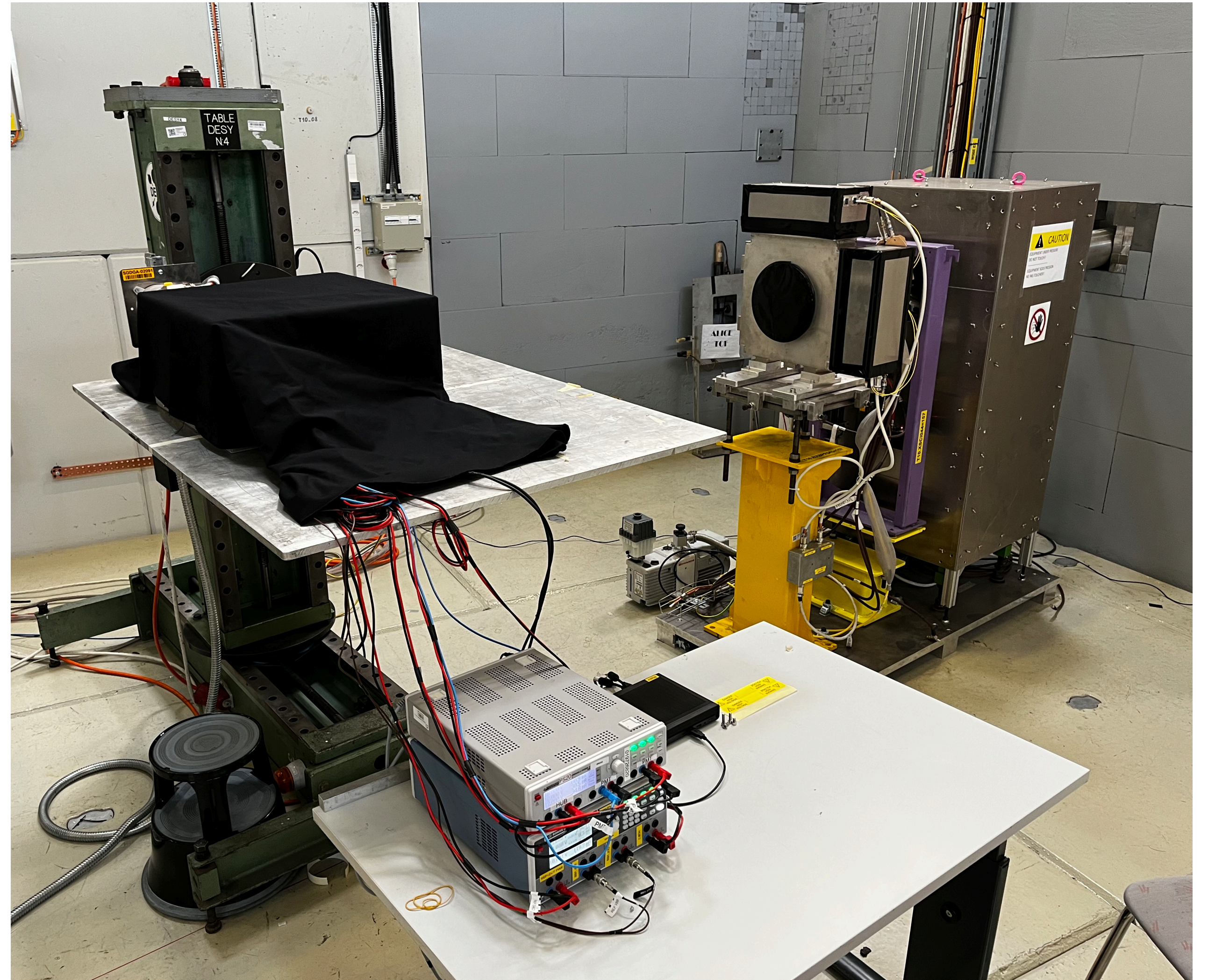
- First “manual” alignment with a laser
- Connect power, connect to the PC
- Refine alignment with beam + eudaq hit display

## Calibration of the PMTs

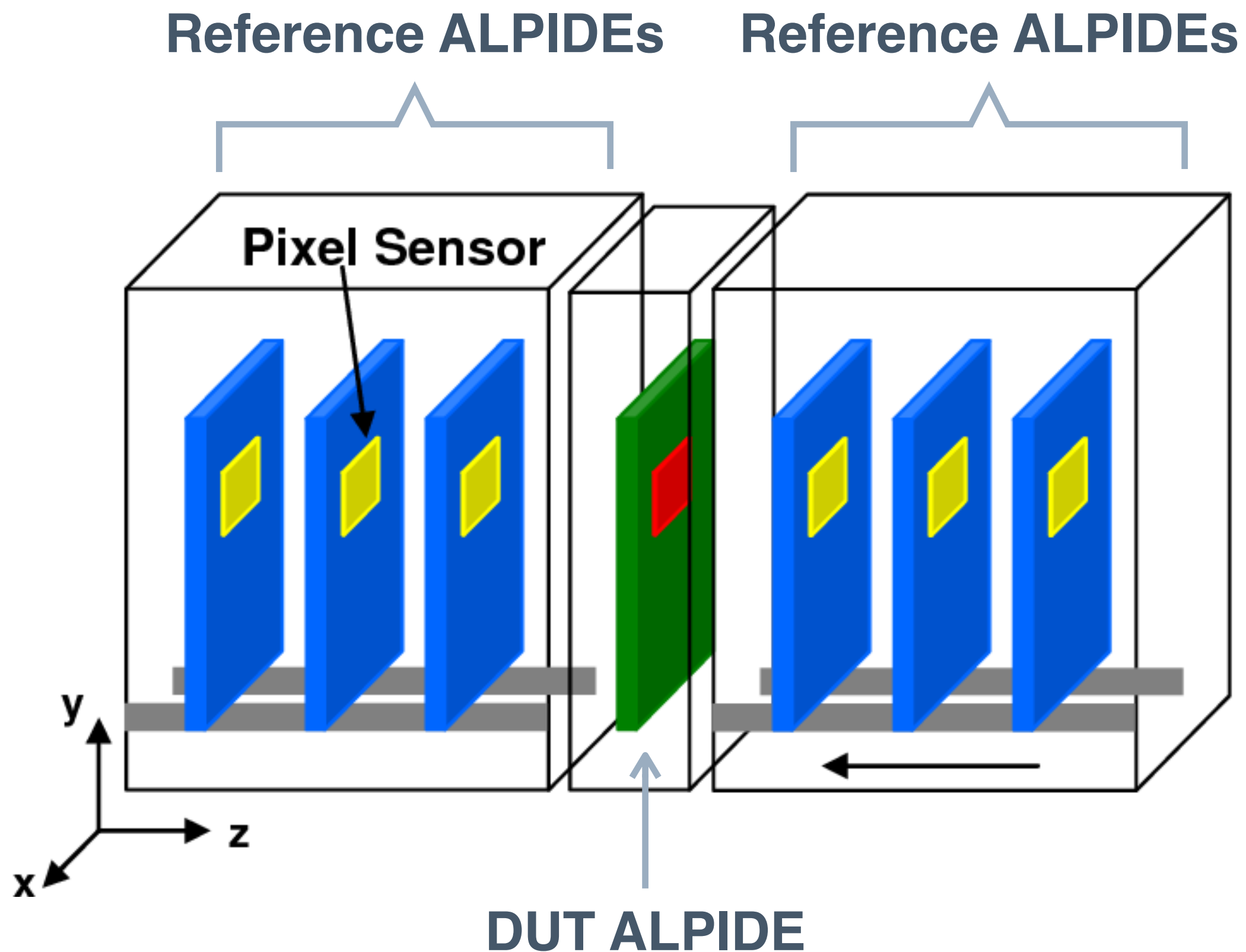
- Gain and threshold adjustment

## Optimization of the veto time

- Improve rate of data taking
- Reduce pile-up in the reference + DUT planes



# Data analysis: primary goals



- 1) ALPIDE VCASN scans (internal threshold)**
  - Data for range of VCASN values with vbb at 3V and 0V
- 2) ALPIDE data with vbb = 0V**
  - New data! ALPIDEs have not been characterized with this bias
- 3) Experiment and optimize process for MOSS test-beam**
  - Prepare for MOSS telescope
  - Establish data collection and analysis pipeline

# Overview of the data taking strategy

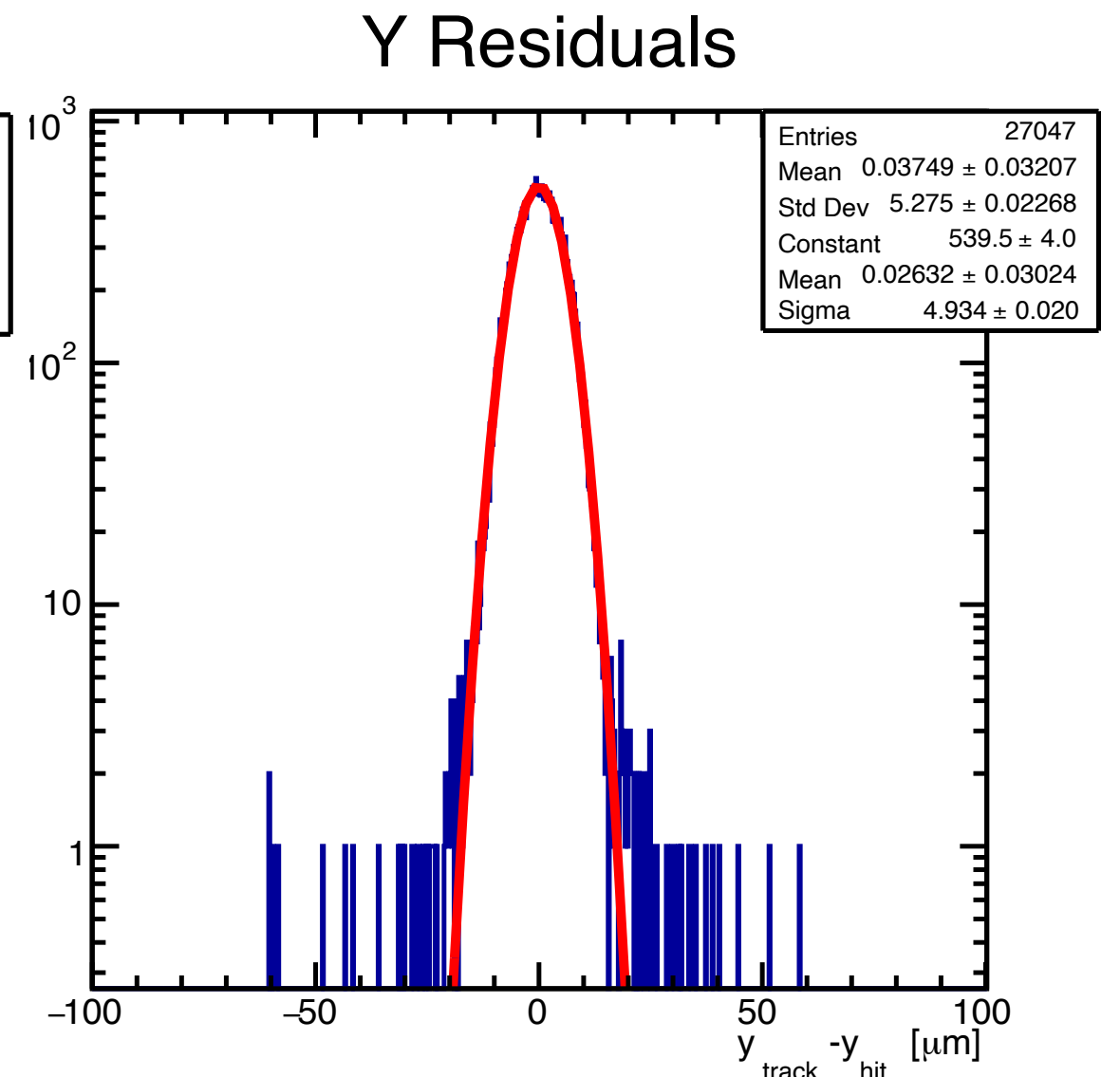
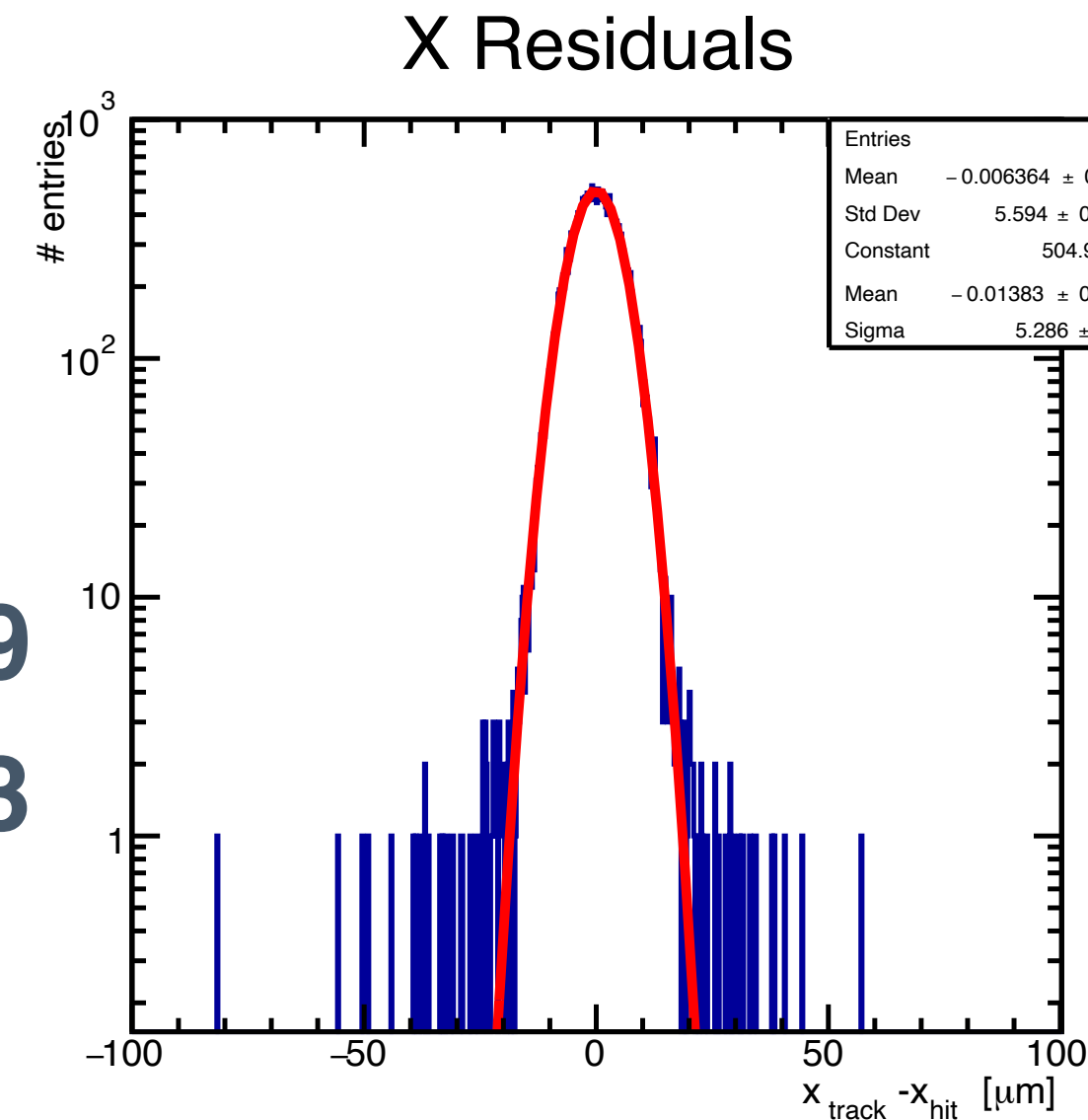
## During Run: Checks with EUDAQ2

- Hit maps → Is telescope aligned to beam?
- Correlations → Are DUT + references working together?
- Hits per event → Reasonable? Pileup issues?

**3V**

**x: 5.29**

**y: 4.93**



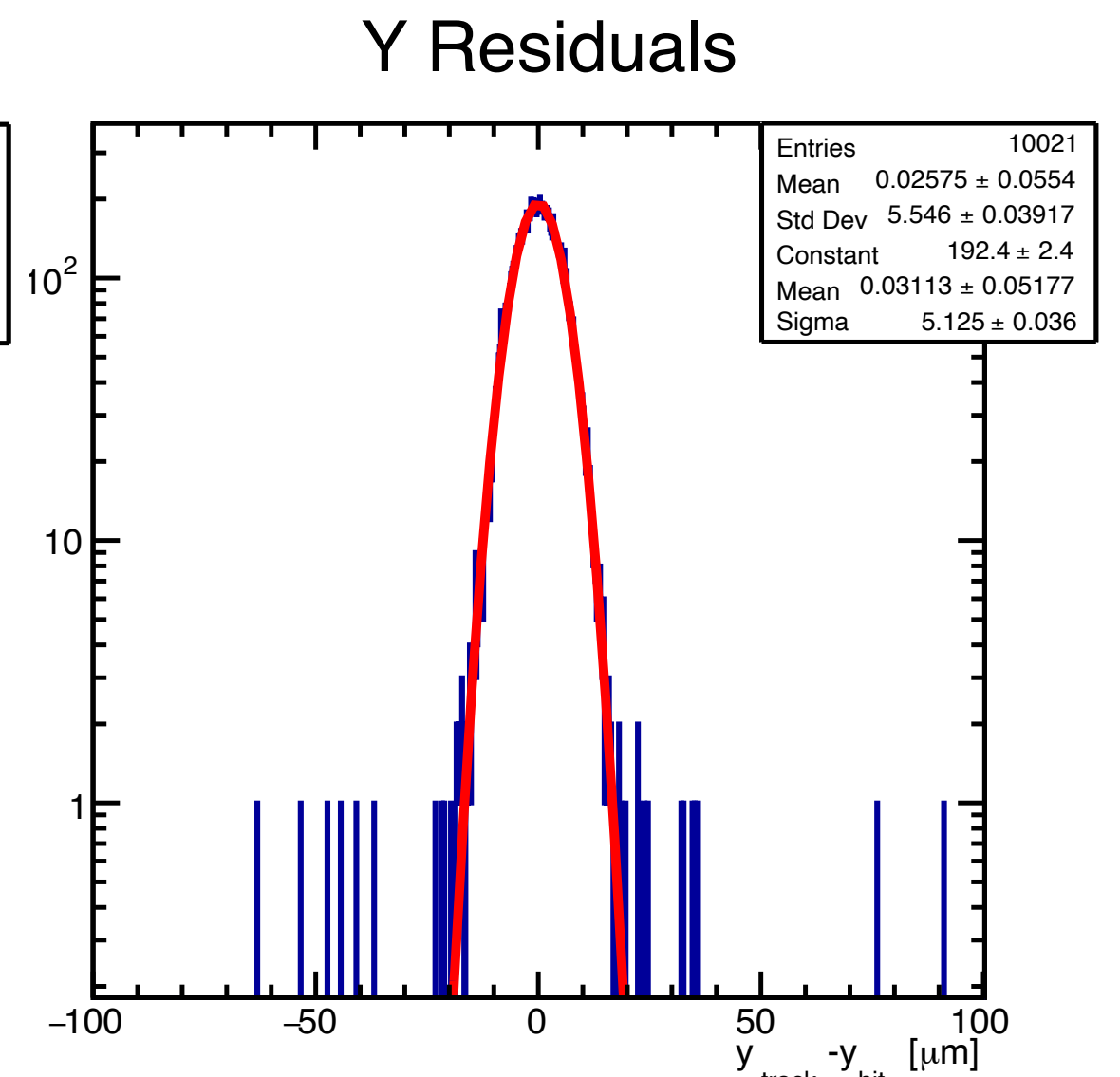
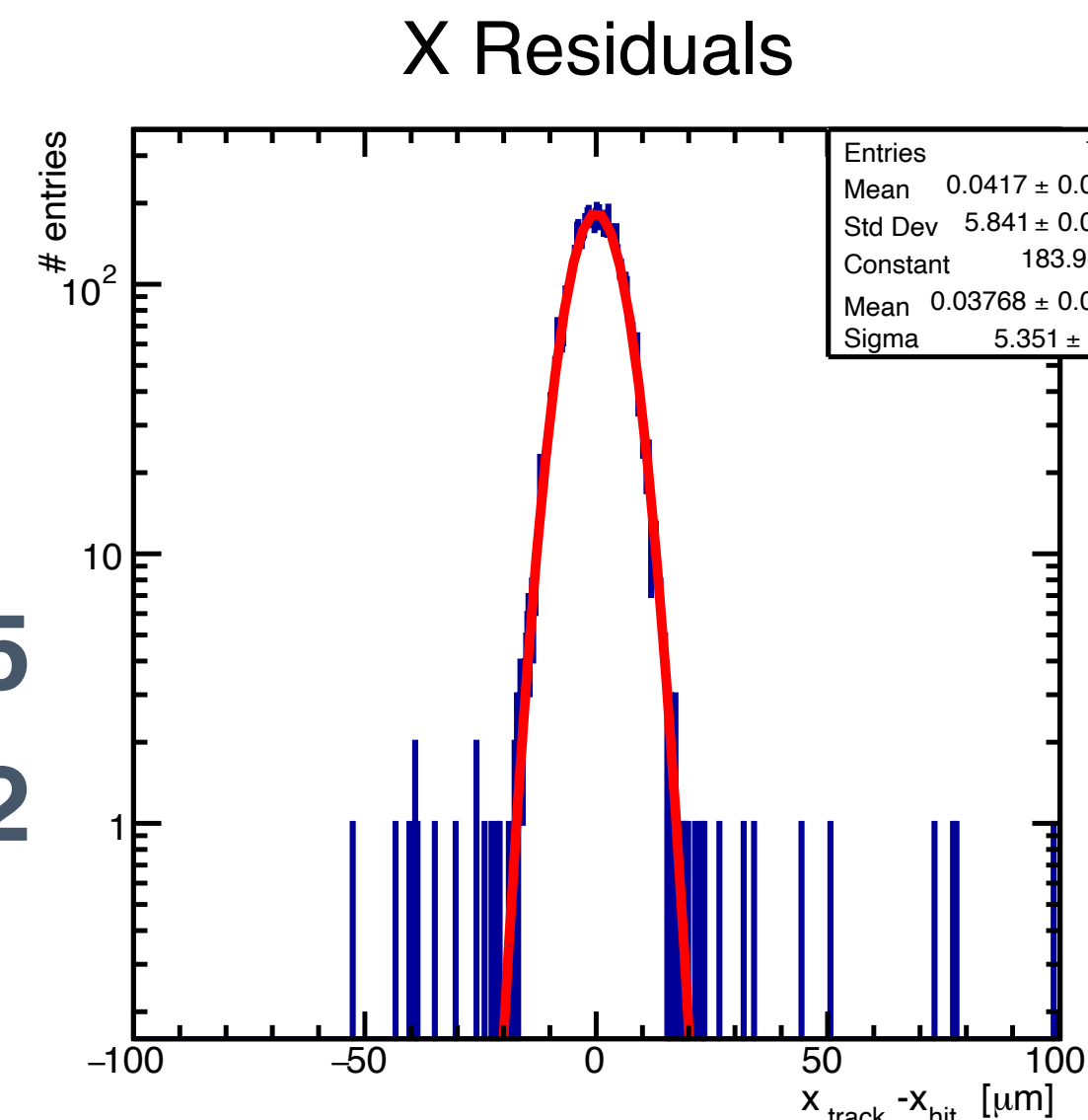
## After Run: Analysis with Corryvreckan

- Align DUT ALPIDE with reference ALPIDE
- Ensure usable tracks with data
- Residuals → Alignment between refs & DUT
- Clusters, cluster sizes → DUT performance, noise

**0V**

**x: 5.35**

**y: 5.12**



**Recent activities at CERN:**

**first test beams with the MOSS!**



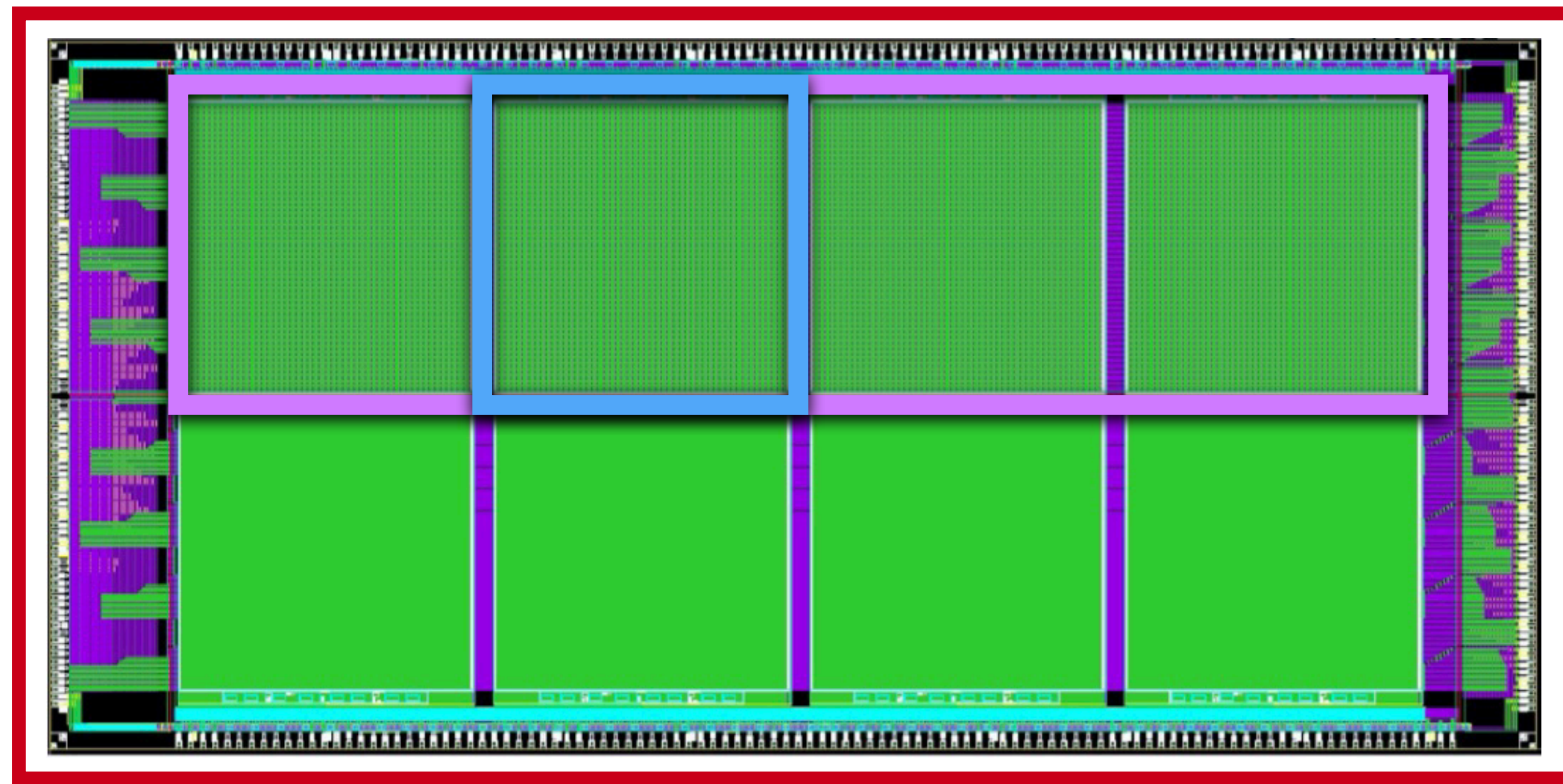
# Overview of the MOSS

(Monolithic Stitched Sensor)

**10 Repeated Sensor Units (RSU)**

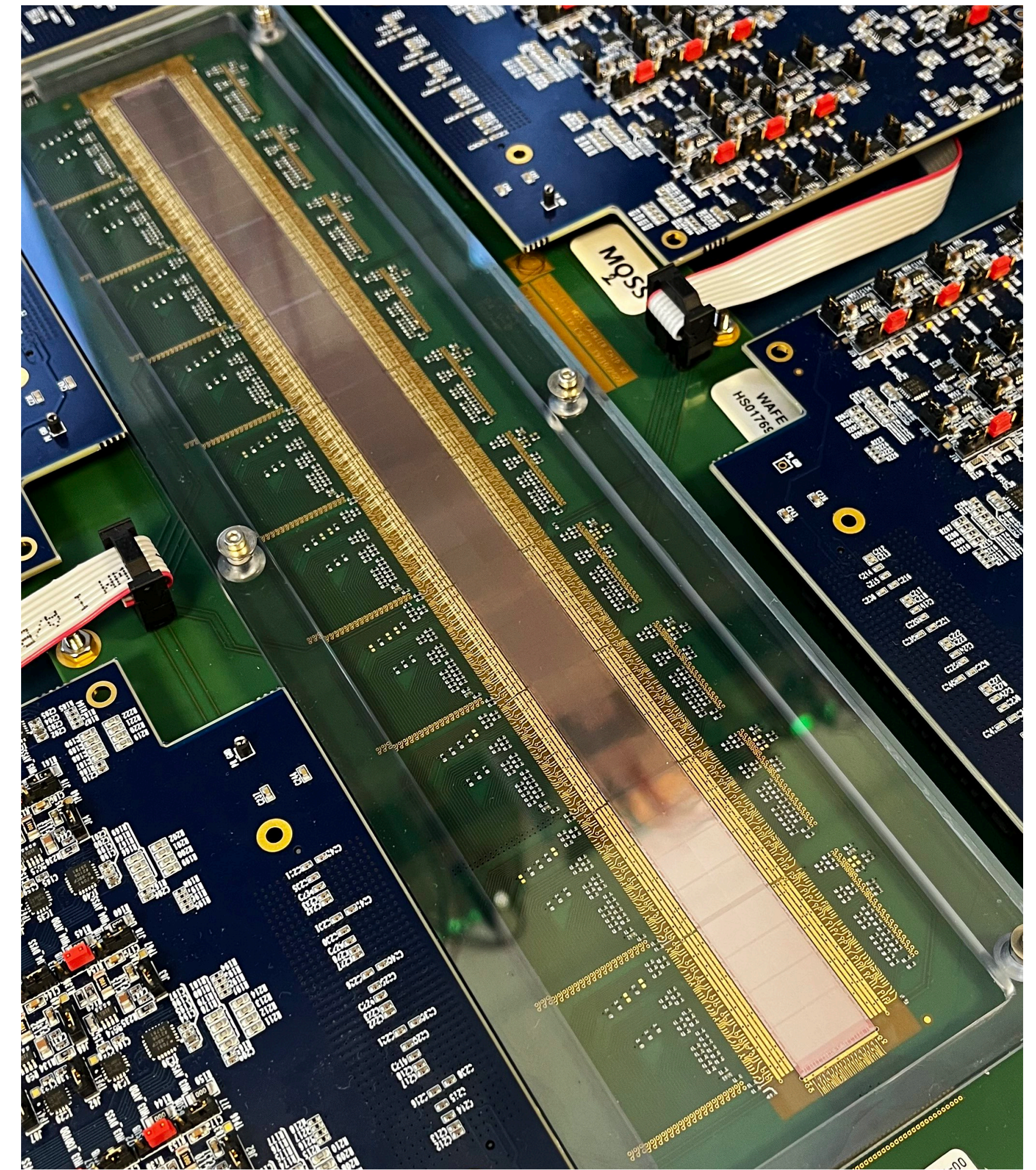
↳ **2 Half-Units (HU)** per RSU (top & bottom have diff. pitch)

↳ **4 Regions** per HU (each with diff. transistors)

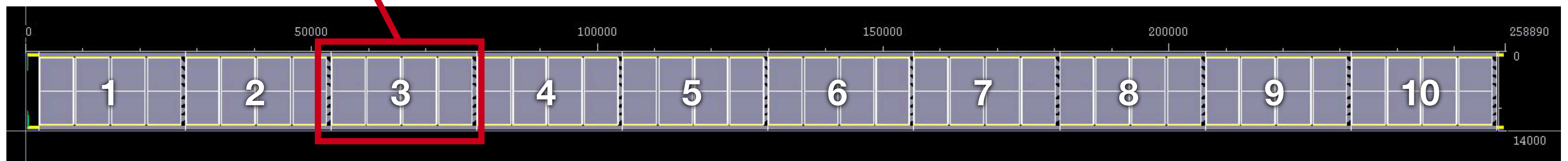


**Top:**  
256 x 256 pixels  
Pitch: 22.5  $\mu\text{m}$

**Bottom:**  
320 x 320 pixels  
Pitch: 18  $\mu\text{m}$



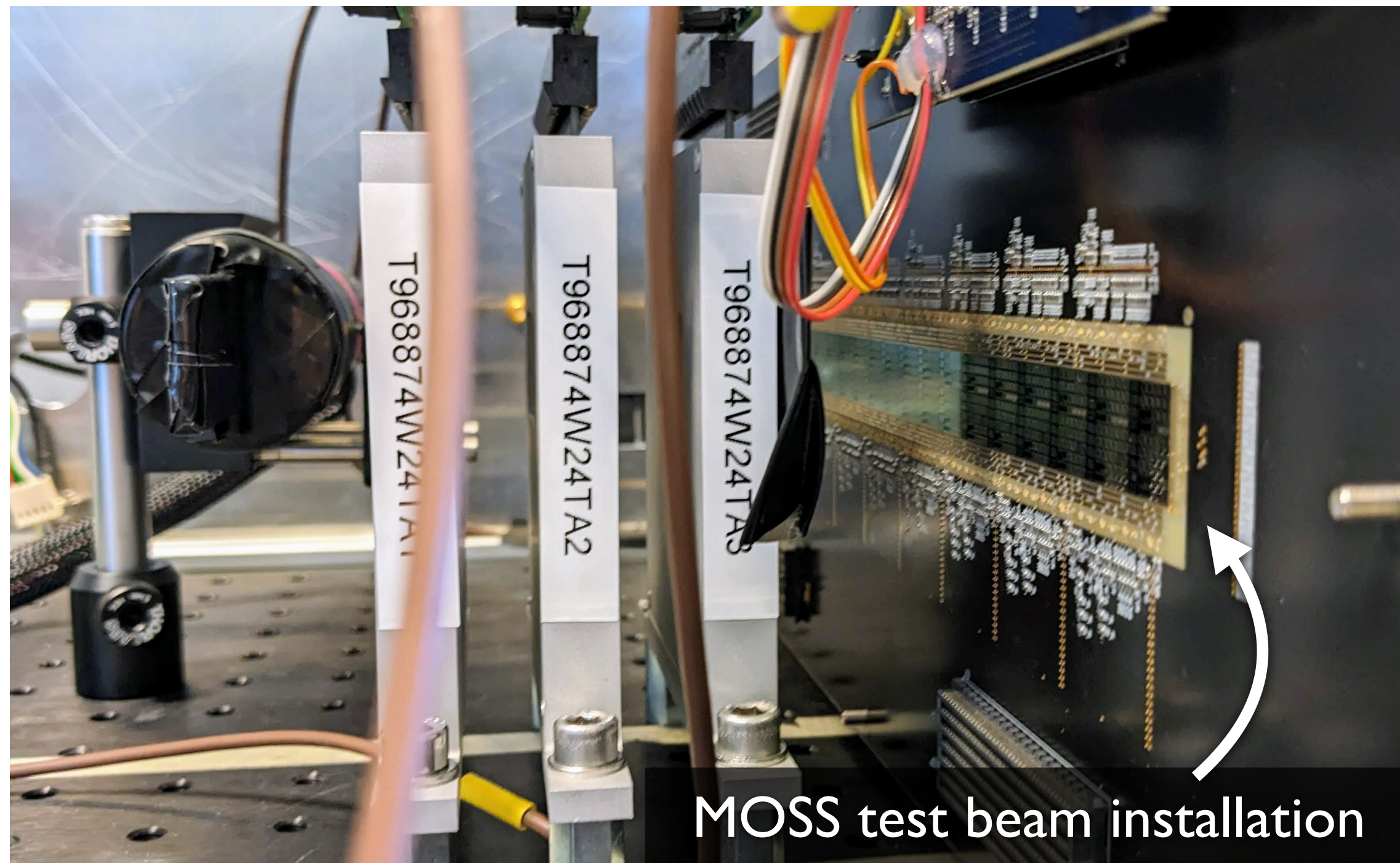
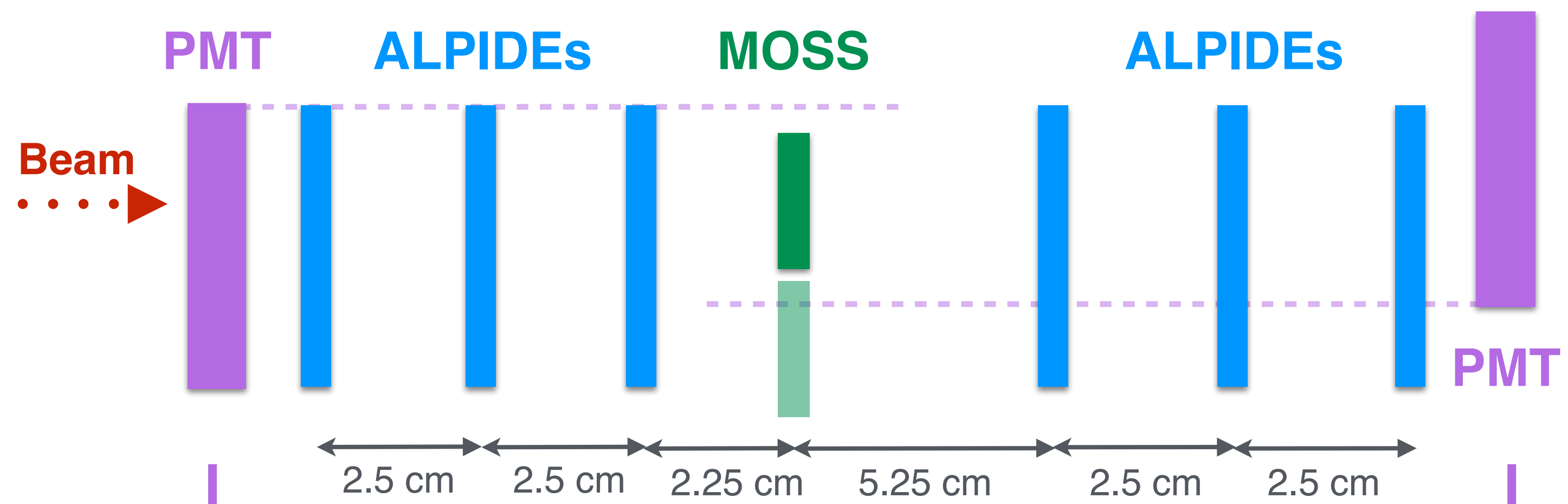
25.9 cm



1.4 cm

# MOSS telescope setup

- 6x ALPIDE reference planes
- Trigger: 2 PMTs in coincidence
- 1 MOSS as DUT



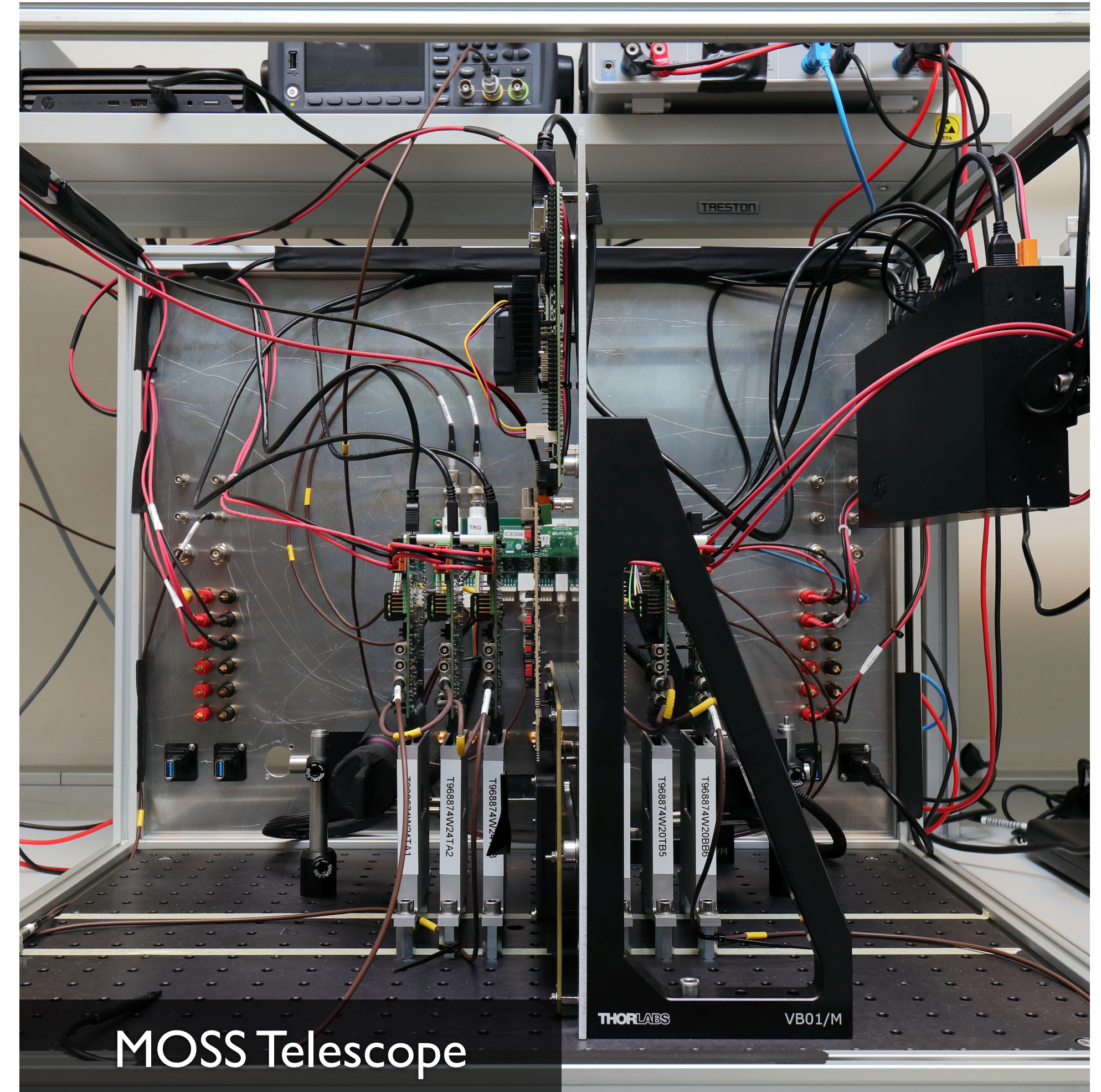
# Test beam at the PS: plan and schedule

## Timetable:

- PS test beam 5 - 19 July
- MOSS in beam since 14 July
- Just 5 weeks after the bonded MOSS arrived at CERN!

## Beam configuration:

- T10@PS: **10 GeV negative hadrons**
- both low-intensity and high-intensity runs



## Goals of the test:

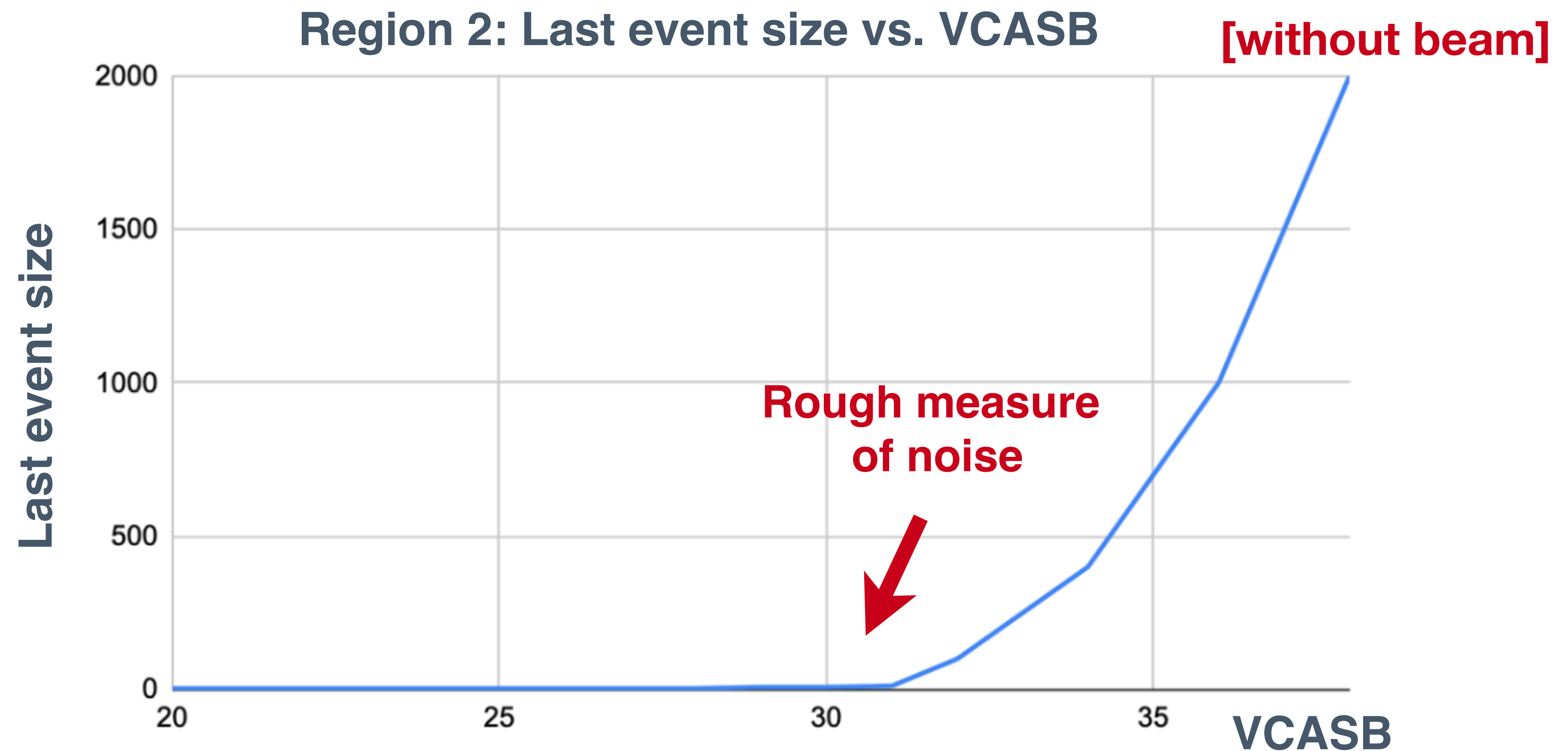
- Observe and characterize the very first signals in the MOSS
- Characterize efficiency and resolution as a function of tension VCASB (**see next slide**)

# MOSS 'Word scan' vs VCASB → noise level

Number of words of the last event recorded by the online DAQ system (4 words = empty event)

→ rough estimation of the noise level of the MOSS

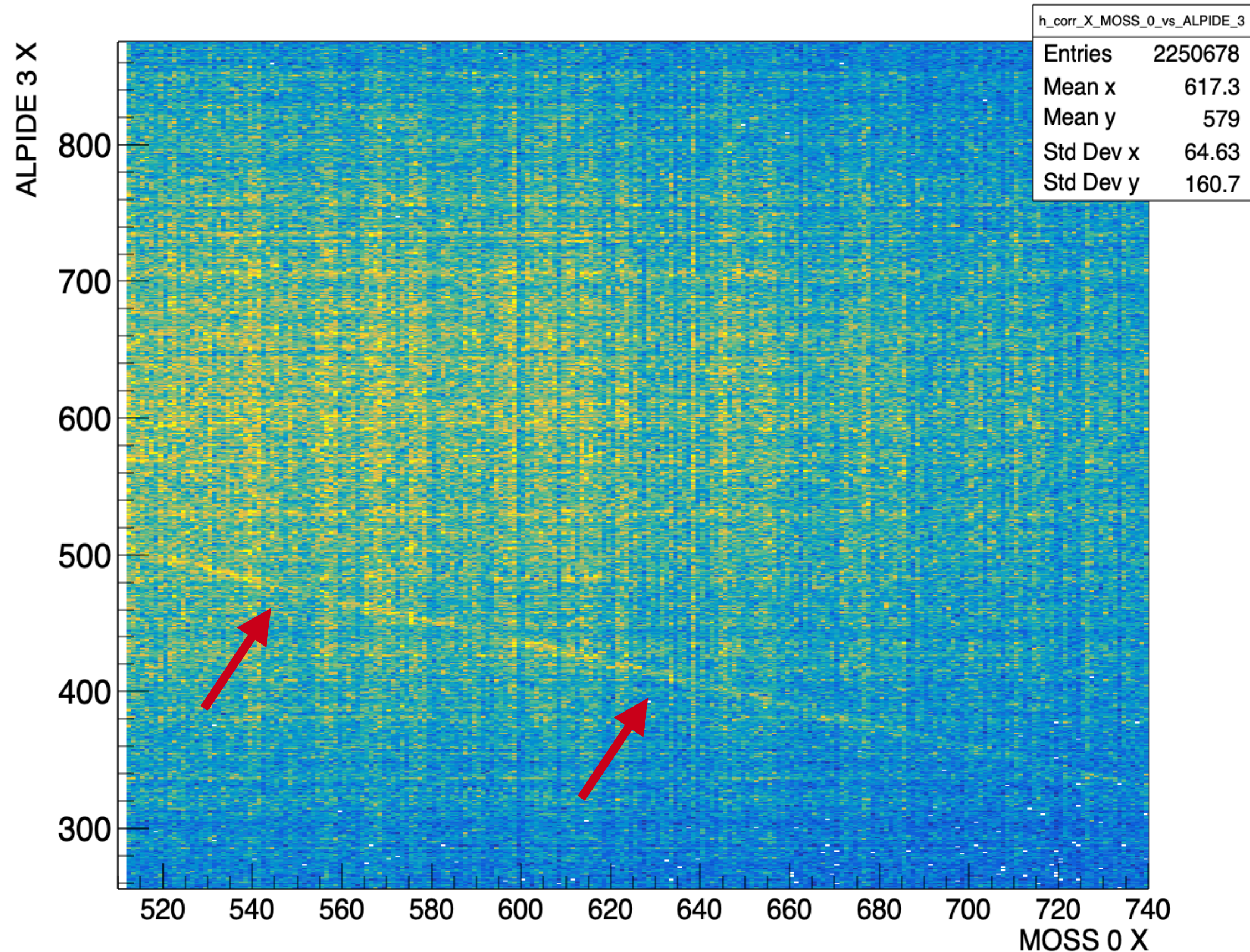
VCASNB	Last event size (n. of words)
36	~ 1000
34	~ 400
32	~ 100
31	12
30	8
29	8
28	4
26	4
24	4
22	4
20	4



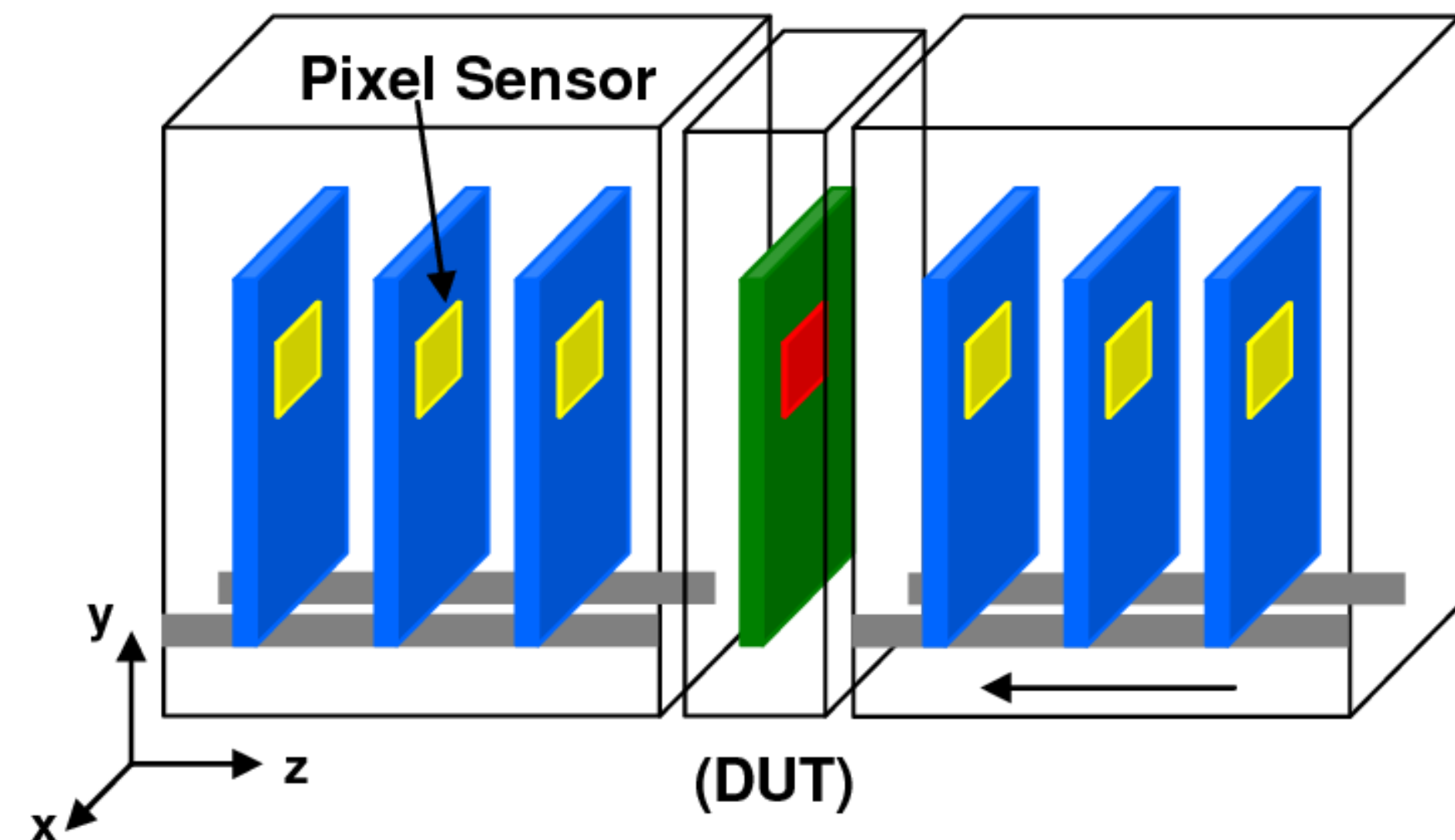
# First correlation seen on ALPIDE(s)–MOSS!

(with high-intensity beam)

X Correlation of MOSS 0 and ALPIDE 3



**Region 2, VCASB=26**



Correlation between the MOSS signal and the one in any of the ALPIDE reference planes:

- both ALPIDEs and MOSS are “seeing” the passage of the same particle trajectory

# Data taking strategy and collected samples

## Large datasets collected in low-intensity mode:

- Low-intensity runs → collimators  $\pm 3.0$  cm
  - Cleaner and higher-luminosity samples (milder trigger veto)
- 20k trigger events per VCASB level
  - ~1 MOSS hit per event
  - ~18k ALPIDE tracks per set → ~10% through MOSS

REGION	0	1	2	3
VCASB steps	[3,25] in steps of 2	[7,23] in steps of 2	[4,30] in steps of 2	-
Statistics	12 x 20k	9 x 20k	13 x 20k	-
Beam Intensity	low	high*	low	-

*\*Different beam settings - data is not reliable*

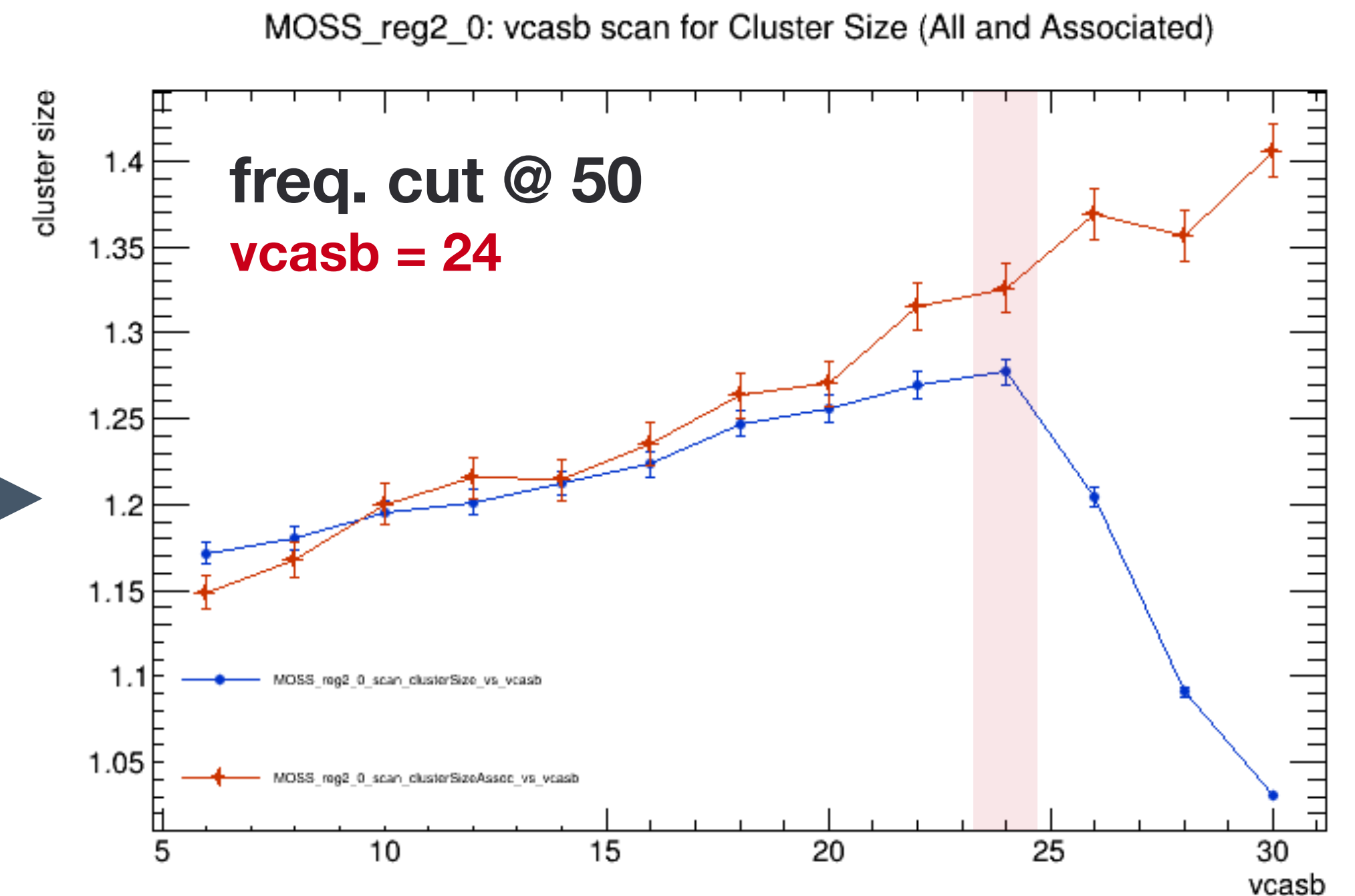
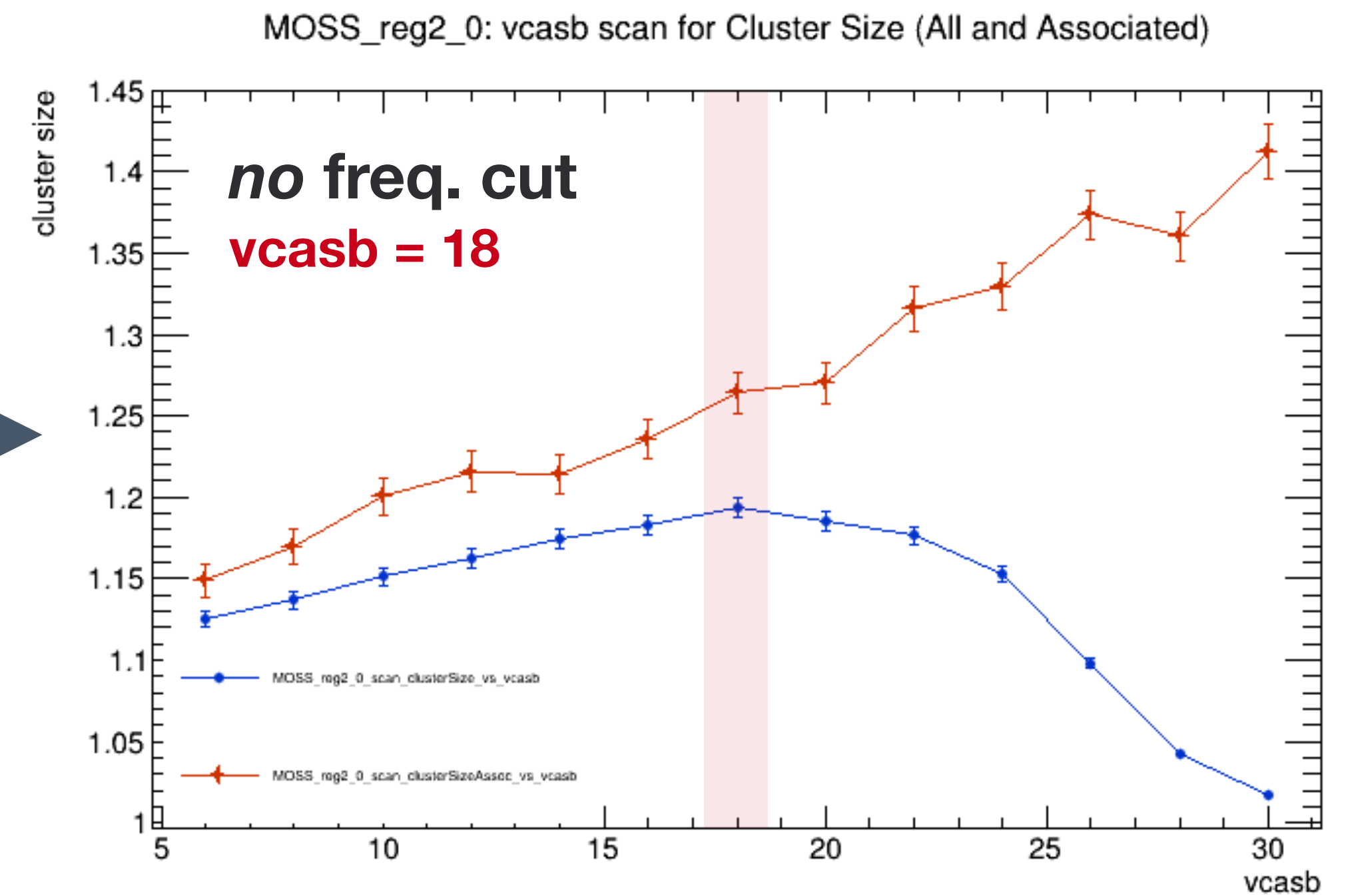
# MOSS analysis: masking noisy pixels

## Apply frequency cut to automatically mask

- Pixel is masked if it satisfies:  

$$[\text{\#hits}] \geq [\text{freq}] \times [\text{avg. hits per event}]$$
- Peak cluster size **without cuts** is at  $\text{vcasb} = 18$ 
  - Much lower than expect, **but...**
- For frequency  $\geq 50$ , **peak shifts to  $\text{vcasb} = 26$** 
  - This is close to “manual scan” results!**

	Manual	No Cut	Cut @ 50
<b>Region 2</b>	<b>~26</b>	<b>18</b>	<b>24</b>
Region 0	~16	13	13



# MOSS analysis: alignment process

- Set MOSS at origin in Z
- Use ALPIDE 2 as “reference” (stays ~fixed, closest to MOSS)
- Time cuts with MOSS are set to 1e99 or turned off

## Corryvreckan Steps

### 1. Masking

Mask with:

**frequency\_cut=-1**

### 2. Prealignment

Broader settings:

**max\_rms=15mm**

**range\_abs=20mm**

### 3. Alignment 1

**Excludes DUT**,  
aligns ALPIDEs only  
(Tracking4D &  
AlignementMillipede)

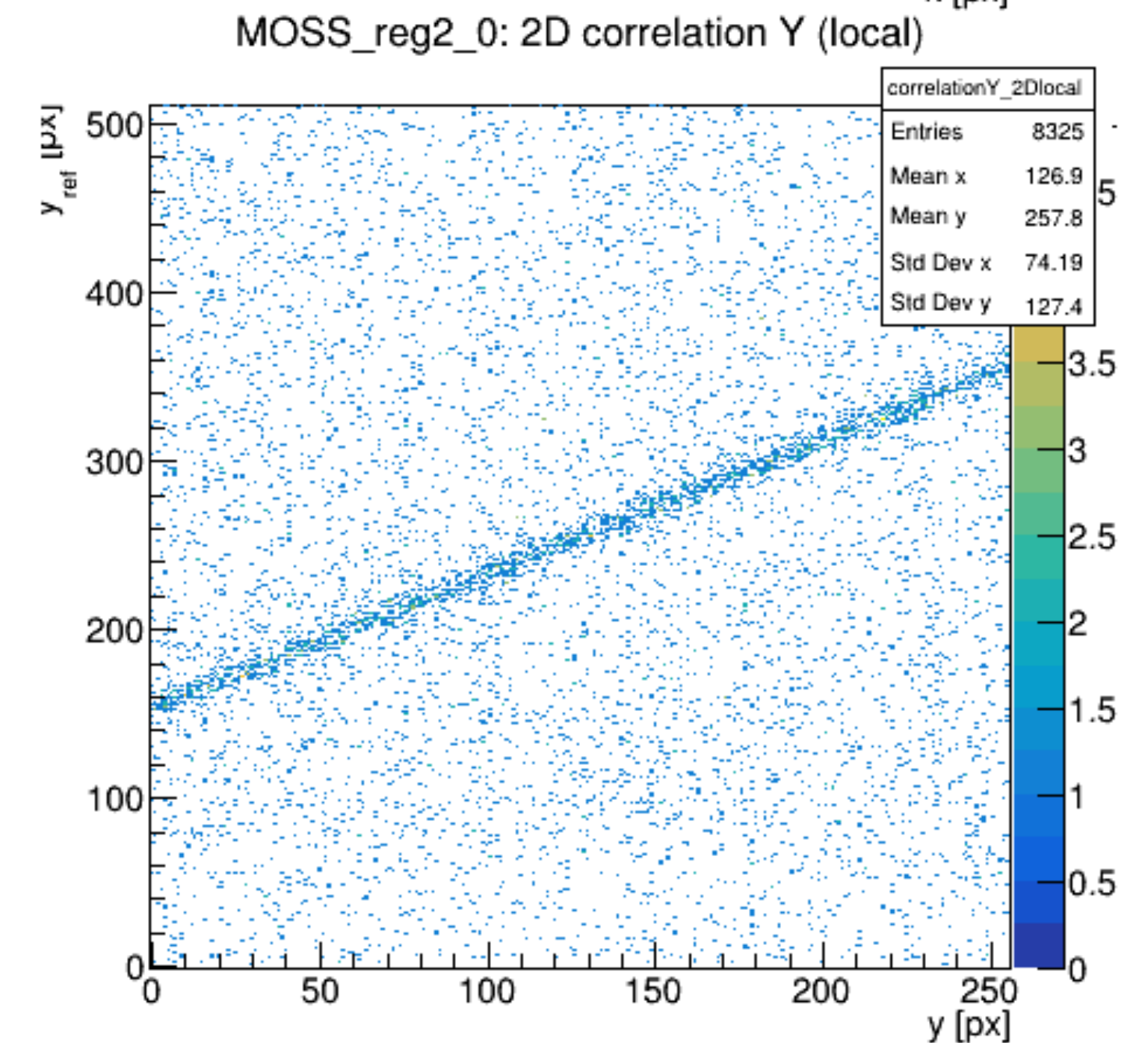
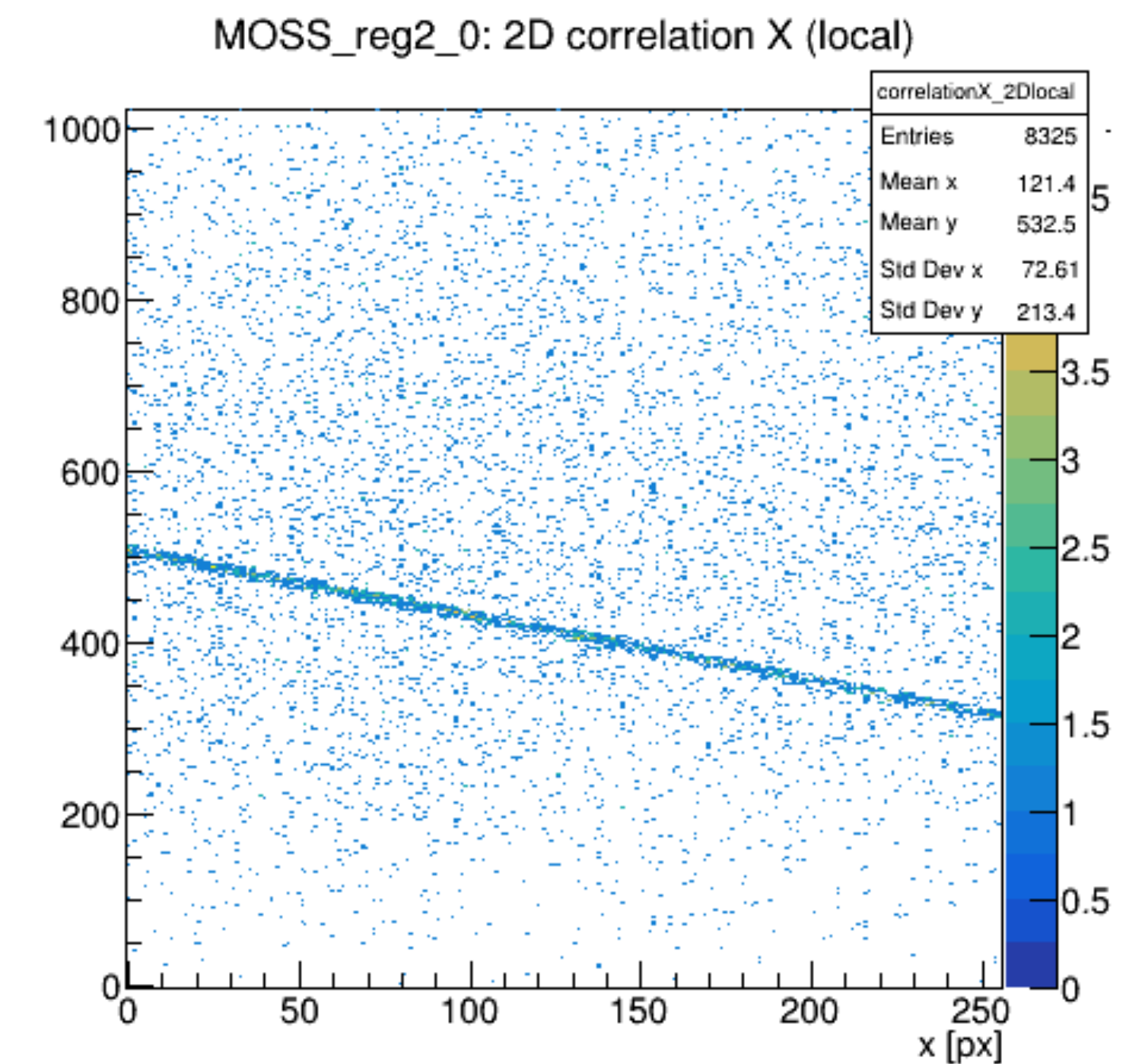
### 4. Alignment 2

**Includes DUT**, aligns  
MOSS with ALPIDEs  
(Tracking4D &  
AlignementMillipede)

### 5. Analysis

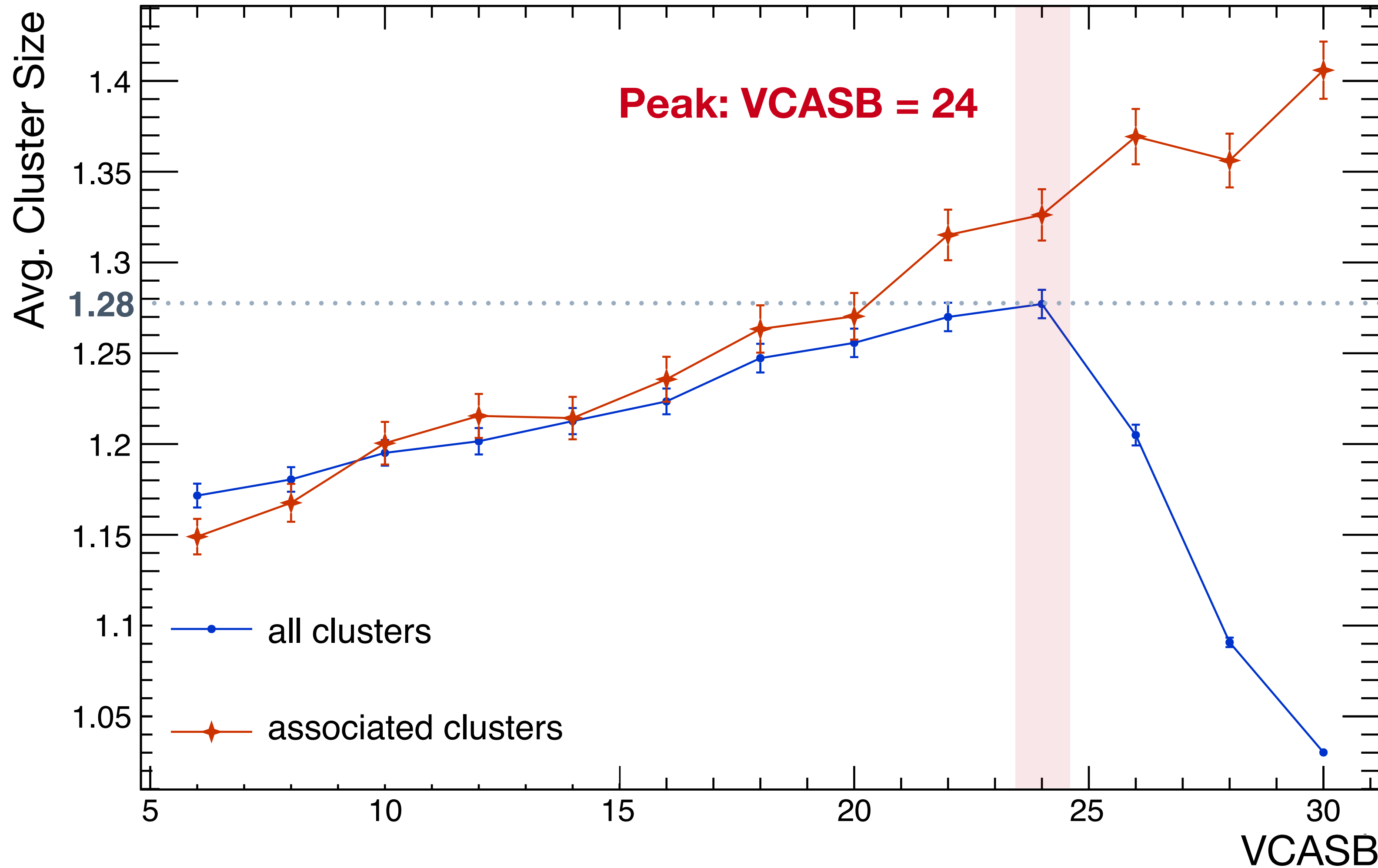
No major changes

**Two Alignment Steps**





# Region 2: $\langle$ Cluster size $\rangle$ vs VCASB



VCASB is **inversely proportional** to threshold

## Why the peak?

- Associated cluster size increases as threshold decreases (charge on neighboring pixels)
- At a point, pixels become noisy and 1-pixel cluster noise dominates

Increasing VCASB  
*Decreasing* Threshold

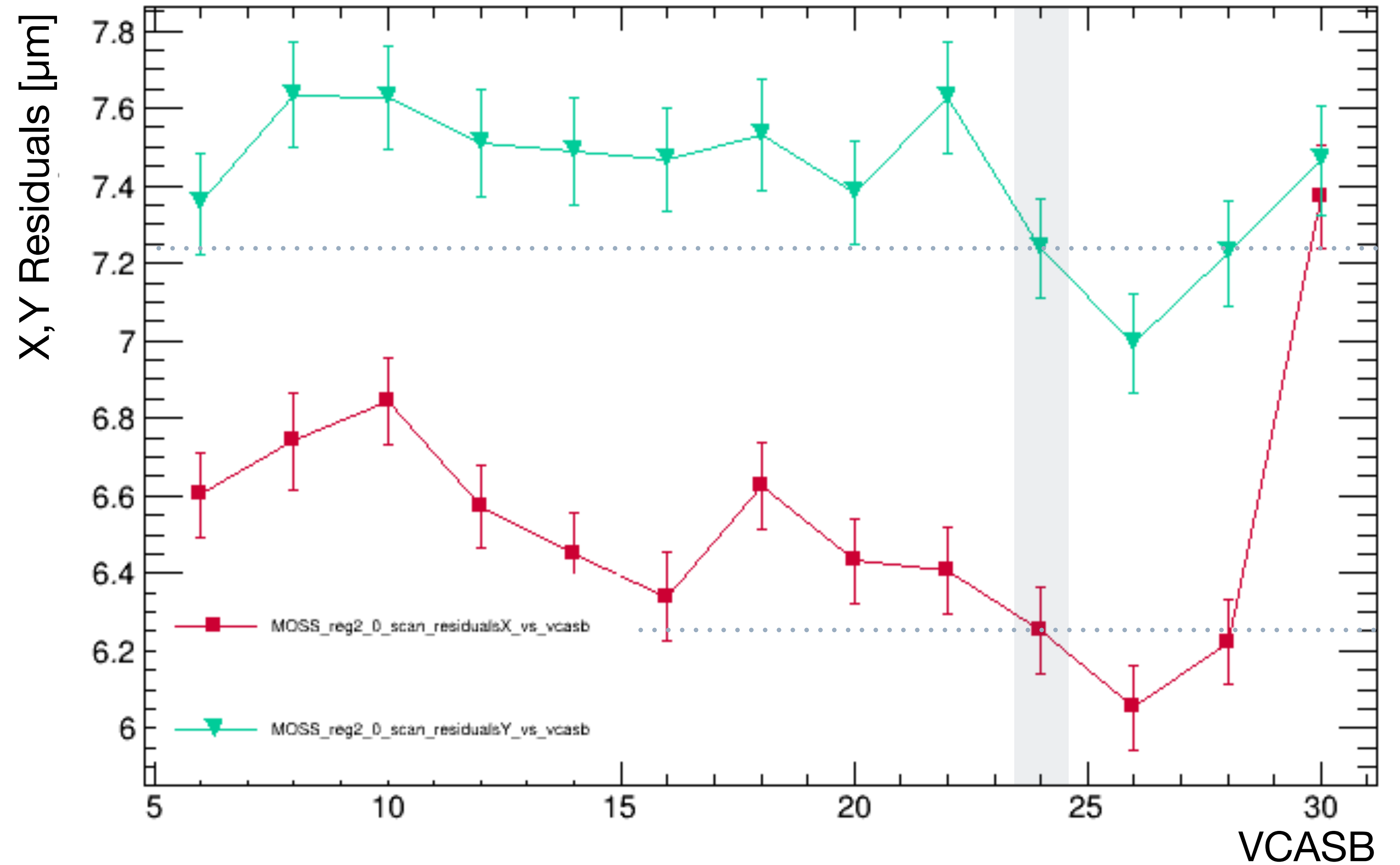
# MOSS Alignment: Region 2 Residuals

## Region 2 (for VCASB = 24)

- X Residuals: **6.25  $\mu\text{m}$**
- Y Residuals: **7.25  $\mu\text{m}$**

## Significant asymmetry between X & Y

- Expected cause: ALPIDE pixels have difference X, Y pitch
- Still need to subtract telescope residuals



# Summary and next steps

- **Major contribution to the R&D, construction, installation and commissioning of the SVT innermost layers**
  - ITS3 as the technological baseline, but with a lot of additional challenges!
- **MIT will profit from a CERN-based laboratory to maximize the knowledge transfer from ALICEITS3 to ePIC SVT**
- **Good plan from the near to the far future, with several aspects are still being optimized/finalized.**
  - any feedback/suggestion is very welcome
- **Already delivering good results!**
  - Our CERN team is providing major contributions to the MOSS first test beam
  - Ramping up the activities at Bates for the mechanical design and R&D
  - A lot of opportunities for students and postdocs to have an impact on the project!

**BACKUP slides**